# Accessories



# PROFINET

E84AYCER

Inverter Drives 8400

Communication manual EN





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### Contents

This documentation exclusively describes the E84AYCER communication module (PROFINET).



### Note!

This documentation supplements the **mounting instructions** supplied with the communication module and the **hardware manual "Inverter Drives 8400"**.

The features and functions of the communication module are described in detail.

Examples illustrate typical applications.

This documentation also contains...

- Safety instructions that must be observed
- The most important technical data of the communication module
- Information about the versions of the Lenze standard devices to be used
- · Notes on troubleshooting and fault elimination

The theoretical context is only explained as far as it is required for understanding the function of the communication module.

Depending on the software version of the inverter and the »Engineer« software installed, the screenshots in this documentation may deviate from the »Engineer« representation.

This documentation does not describe the software of other manufacturers. No responsibility is taken for corresponding information given in this documentation. Information on how to use the software can be obtained from the documents of the host system (master).

All brand names mentioned in this documentation are trademarks of their corresponding owners.



Detailed information on PROFINET can be found on the homepage of the PROFIBUS user organisation which also develops the PROFINET communication technology:

www.profibus.com

### Target group

This documentation addresses to persons who configure, install, commission, and maintain the networking and remote maintenance of a machine.

# -``@\_- Tip!

Information and software updates for Lenze products can be found in the download area at:

\_\_\_\_\_\_

www.Lenze.com

### Information regarding the validity

The information given in this documentation is valid for the following devices:

Extension module	Type designation	From hardware versi- on	From software versi- on
PROFINET communication module	E84AYCER	VA	02.00

Document history

### 1.1 Document history

Versior	ı		Description
3.0	02/2019	TD23	General revision
2.0	11/2010	TD17	<ul> <li>General revision</li> <li>Update for SW version 02.00</li> </ul>
1.0	04/2010	TD17	First edition

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Conventions used

### 1.2 Conventions used

This documentation uses the following conventions to distinguish between different types of information:

\_\_\_\_\_

Type of information	Highlighting	Examples/notes
Spelling of numbers		
Decimal	Normal spelling	Example: 1234
Hexadecimal	0x[0 9, A F]	Example: 0x60F4
Binary • Nibble	In inverted commas Point	Example: '100' Example: '0110.0100'
Decimal separator	Point	The decimal point is always used. For example: 1234.56
Text		
Program name	» «	PC software Example: Lenze »Engineer«
Control element	Bold	The OK button / The Copy command / The Properties tab / The Name input field
Hyperlink	Underlined	Optically highlighted reference to another topic. Can be activated with a mouse-click in this documentati- on.
lcons	-	
Page reference	(💷 8)	Optically highlighted reference to another page. Can be activated with a mouse-click in this documentati- on.
Step-by-step instructions	e e e e e e e e e e e e e e e e e e e	Step-by-step instructions are indicated by a picto- graph.

Terminology used

### 1.3 Terminology used

Term	Meaning
Inverter	Lenze inverters of the "Inverter Drives 8400" product series for which the com-
Standard device	<ul> <li>Application module can be used.</li> <li>Application as directed (E112)</li> </ul>
»Engineer«	Lenze PC software which supports you during the "Engineering" process (para- meterisation, diagnostics, and configuration) throughout the whole life cycle, i. e. from planning to maintenance of the machine commissioned.
Code	Parameter which serves to parameterise and monitor the inverter. In normal usage, the term is usually referred to as "Index".
Subcode	If a code contains several parameters, they are stored in "subcodes". This manual uses a slash "/" as a separator between code and subcode (e.g. "C00118/3"). This term is also referred to as "subindex" in common parlance.
Lenze setting	This setting is the default factory setting of the device.
Basic setting	
HW	Hardware
SW	Software
I/O controller	PROFINET master The I/O controller takes over the master function for data communication of the decentralised field devices. The I/O controller usually is the communication in- terface of a PLC.
I/O device	PROFINET slave
IO supervisor	Engineering and diagnostics tools The IO supervisor can access process data, diagnostic data, and alarm data.

Notes used

### 1.4 Notes used

The following signal words and symbols are used in this documentation to indicate dangers and important information:

\_\_\_\_\_

### Safety instructions

Layout of the safety instructions:

### Pictograph and signal word!

(characterise the type and severity of danger)

Note

(describes the danger and gives information about how to prevent dangerous situations)

Pictograph	Signal word	Meaning
A	Danger!	Danger of personal injury through dangerous electrical voltage Reference to an imminent danger that may result in death or serious perso- nal injury if the corresponding measures are not taken.
	Danger!	Danger of personal injury through a general source of danger Reference to an imminent danger that may result in death or serious perso- nal injury if the corresponding measures are not taken.
STOP	Stop!	<b>Danger of property damage</b> Reference to a possible danger that may result in property damage if the cor- responding measures are not taken.

### **Application notes**

Pictograph	Signal word	Meaning
i	Note!	Important note to ensure trouble-free operation
-`	Tip!	Useful tip for easy handling
<b>(bj</b> )		Reference to another document

General safety and application notes

### 2 Safety instructions

# Note!

It is absolutely vital that the stated safety measures are implemented in order to prevent serious injury to persons and damage to material assets.

Always keep this documentation to hand in the vicinity of the product during operation.

### 2.1 General safety and application notes



# Danger!

If the following basic safety measures are disregarded, severe injuries to persons and damage to material assets may result.

- Lenze drive and automation components ...
  - must only be used as directed.
  - Application as directed (112)
  - must never be commissioned if they display signs of damage.
  - must never be technically modified.
  - must never be commissioned if they are not fully mounted.
  - must never be operated without required covers.
  - during and after operation can have live, moving and rotating parts, depending on their degree of protection. Surfaces can be hot.
- The following applies to Lenze drive components ...
  - only use the accessories approved.
  - Only use original manufacturer spare parts.
- Observe all specifications contained in the enclosed documentation and related documentation.
  - This is the precondition for safe and trouble-free operation and for obtaining the product features specified.
    - Product features (III 13)
  - The specifications, processes, and circuitry described in this document are for guidance only and must be adapted to your own specific application. Lenze does not take responsibility for the suitability of the process and circuit proposals.
- All works on and with Lenze drive and automation components must only be carried out by qualified personnel. According to IEC 60364 or CENELEC HD 384 these are persons who ...
  - are familiar with installing, mounting, commissioning, and operating the product.
  - who have the corresponding qualifications for their work.
  - who know and can apply all regulations for the prevention of accidents, directives, and laws applicable at the place of use.

# Safety instructions

Device and application-specific safety instructions

### 2.2 Device and application-specific safety instructions

- During operation, the communication module must be securely connected to the standard device.
- Always use a separate power supply unit safely separated according to EN 61800-5-1 ("SELV/ PELV") in every control cabinet for external voltage supply.
- Only use cables corresponding to the given specifications.
   Ethernet cable specification (
   <sup>1</sup> 30)



#### Documentation for the standard device, control system, system/machine

All the other measures prescribed in this documentation must also be implemented. Observe the safety instructions and application notes contained in this manual.

### 2.3 Residual hazards

#### **Protection of persons**

• If the Inverter Drives 8400 are operated on a phase-earthed mains with a rated mains voltage of ≥ 400 V, external measures need to be implemented in order to ensure protection against accidental contact.

▶ Protective insulation (□ 16)

#### **Device protection**

• The communication module contains electronic components which may be damaged or destroyed by electrostatic discharge.

▶ Installation (□ 22)

Application as directed

# **3 Product description**

### 3.1 Application as directed

The communication module ...

• is an accessory module that can be used in conjunction with the following standard devices:

Product series	Type designation	From software version
Inverter Drives 8400 StateLine	E84AVSCxxxxx	05.00
Inverter Drives 8400 HighLine	E84AVHCxxxxx	05.00
Inverter Drives 8400 TopLine	E84AVTCxxxxx	01.00

- is a device intended for use in industrial power systems.
- should only be used under the operating conditions prescribed in this documentation.
- should only be used in PROFINET networks.

Any other use shall be deemed inappropriate!

### 3.2 Identification

Type designation and hardware and software version of the communication module are indicated on the nameplate:



[3-1] Identification data

**Product features** 

### 3.3 Product features

• Interface module for the PROFINET IO communication system to the expansion slots of the Inverter Drives 8400

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- The communication module can either be supplied internally by the standard device or externally by a separate voltage source.
- Support of the I&MO...4 functionality for the identification of the standard device
- Automatic detection of the baud rate 100 Mbps
- A line topology is enabled by the integrated 2-port switch.
- Support of the LLDP protocol for the topology recognition
- Support of the SNMP protocol for diagnostic purposes
- Support of the MRP (Media Redundancy Protocol)
   The Inverter Drive 8400 can be integrated into a ring topology as a client node.
- Access to all Lenze parameters
- An online connection via PROFINET can be established using the Lenze »Engineer«.

# **Product description**

Connections and interfaces

### 3.4 Connections and interfaces

- 2 RJ45 sockets for the PROFINET connection
- 2-pole plug connector for the external voltage supply of the communication module.
- Front LEDs for diagnosing the ...
  - voltage supply of the communication module;
  - connection to the standard device;
  - PROFINET connection;
  - PROFINET activity.



[3-2] E84AYCER communication module (PROFINET)

# **Technical data**

General data and operating conditions

### 4 Technical data

### 4.1 General data and operating conditions

Range	Values			
Order designation	E84AYCER			
Communication profile	PROFINET			
Communication medium	S/FTP (Screened Foiled Twisted Pair, ISO/IEC 11801 or EN 50173), CAT 5e			
Interface for communication	RJ45: Standard Ethernet (in accordance with IEEE 802.3), 100Base-TX (Fast Ethernet)			
Network topology	Tree, star, and line			
Type of node	I/O device with real time (RT) communication properties			
Number of device nodes	Max. 255 in the subnetwork			
Max. cable length	100 m			
PNO identification number	0x0106			
Device identification (Device ID)	0x8400			
TCP port	8410			
Baud rate	100 Mbps			
Switching method	"Store and forward"			
Switch latency	Approx. 125 μs at max. frame length			
Voltage supply	External supply via separate power supply unit • "+": U = 24 V DC (20.4 V - 0 % 28.8 V + 0 %), I = 140 mA • "-": Reference potential for external voltage supply			
Conformities, approvals	CE 2004/108/EC, EMC Directive 2006/95/EC, Low-Voltage Directive			
	EAC Eurasian conformity TR CU: Technical Regulations of Customs Union			
	TP TC 004/2011 (TR CU 004/2011) About the safety of low voltage equipment			
	TP TC 020/2011 (TR CU 020/2011) Electromagnetic compatibility of technical means			
	UL UL 508C / C22.2 No. 14, Power Conversion Equipment (File-No. E132659)			

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### Hardware manual "Inverter Drives 8400"

Here you can find the **ambient conditions** and data on the **electromagnetic compatibility (EMC)**, which also apply to the communication module.

Protective insulation

### 4.2 Protective insulation

# Danger!

### Dangerous voltage

If the Inverter Drives 8400 are operated on a phase-earthed mains with a rated mains voltage of  $\geq$  400 V, external measures need to be implemented in order to ensure protection against accidental contact.

#### **Possible consequences:**

• Death or severe injuries

#### **Protective measures:**

- If protection against accidental contact is required for the control terminals of the inverter and the connections of the device modules plugged, ...
  - a double isolating distance must exist.
  - the components to be connected must be provided with the second isolating distance.

# Note!

The existing protective insulation in the Inverter Drives 8400 is implemented according to EN 61800-5-1.

The following illustration ...

- shows the arrangement of the terminal strips and the separate potential areas of the Inverter Drive 8400.
- serves to determine the decisive protective insulation between two terminals located in differently insulated separate potential areas.



[4-1] Protective insulation in accordance with EN61800-5-1

Terminal strip	Connection
X100	Mains/DC-bus connection
X101	Relay contact
X105	Motor/brake resistor
X106	Motor PTC
X1	System bus (CANopen)
Х3	Analog inputs/outputs
X4	Digital outputs
X5	Digital inputs
Х6	Diagnostics
MCI	Slot for the communication module
MMI	Slot for the memory module

### Example

Which type of protective insulation is used between the bus terminal of the device module in slot MCI and the X100 mains terminal?

• The separate potential area with the better protective insulation is decisive.

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- The separate potential area of the bus terminal of the device module has a "functional insulation".
- The separate potential area of the mains terminal has a "reinforced insulation".
- Result: The insulation between mains terminal X100 and the bus terminal is of the "reinforced insulation" type.

Protocol data

### 4.3 Protocol data

Range	Values
Process data words (PCD)	Max. 16 process data words (max. 32 bytes)
Acyclic parameter data channel	Limited by the PROFINET frame size

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### 4.4 Communication time

The communication time is the time between the start of a request and the arrival of the corresponding response.

The communication times in the PROFINET network depend on the ...

- processing time in the inverter;
- frame runtime (baud rate / frame length);
- nesting depth of the network.

#### Processing time inside the inverter

Data	Processing time		
Process data	Approx. 2 ms + 0 1 ms + 1 x ms	Update cycle Processing time in the module Runtime of the application task of the technology applicati- on used (tolerance)	
Parameter data	<ul> <li>Approx. 30 ms + a tolerance of 20 ms (typically)</li> <li>For some codes, the processing time may be longer (see software manual/»Engineer« online help for the Inverter Drive 8400).</li> </ul>		

There are no interdependencies between parameter data and process data.

# Technical data

Internal switch latency

### 4.5 Internal switch latency

The integrated 2-port switch causes runtime delays which can be calculated as follows:

Runtime delay = ((36 permanent bytes + process data in bytes) x 8 x 10 nsec) + 4 µsec

#### Example :

20 process data words + 4 PROFIsafe words => 48 bytes

- ((36 permanent bytes + 48 bytes) x 8 x 10 nsec) + 4 μsec
- (84 bytes x 8 x 10 nsec) + 4 μsec
- 6.72 μsec + 4 μsec = **10.72 μsec**

In accordance with the PROFINET specification, the shortest PROFINET I/O frame must have a data length of 72 bytes. If the 36 permanent bytes are subtracted from the 72 bytes, 36 bytes are available for process data. If now less than 36 bytes of process data are used, the PROFINET I/O frame is filled with "zero bytes" until it can be transmitted. As a consequence for the calculation formula, the shortest PROFINET I/O frame with 18 process data words (36 bytes) has always the same length and thus the runtime delay is the same, too.

### Note!

The use of external switches can also lead to runtime delays. Depending on the system constellation, it may be useful to create a star topology or a line/mix topology.

▶ <u>Network topology</u> (□ 26)

# Technical data

Dimensions

### 4.6 Dimensions



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[4-2] Dimensions

Туре	Dimensions [mm]			
	а	b	c	c1
E84AYCER	67	50	57	8

# 5 Installation

# STOP Stop!

### **Electrostatic discharge**

Electronic components within the communication module can be damaged or destroyed by electrostatic discharge.

### **Possible consequences:**

- The communication module is defective.
- Fieldbus communication is not possible or faulty.

### **Protective measures**

• Before touching the module, be sure that you are free of electrostatic charge.

### Installation Mechanical installation

### 5.1 Mechanical installation

The communication module can be plugged in or unplugged from the MCI slot when the inverter is switched on. When the module is plugged in, it is detected automatically, and a function and version plausibility check is executed.

### 5.1.1 Mounting for standard devices of 0.25 kW and 0.37 kW



[5-1] Mounting for standard devices of 0.25 kW and 0.37 kW

### **Mounting steps**

- 1. Use a screwdriver to lever out the cover of the MCI slot of the standard device and remove it (1, 2).
- 2. Loosen the securing screw for the communication module at the standard device (3).
- 3. Insert the communication module into the MCI slot of the standard device (4).
- 4. Tighten the securing screw again (5).

### Installation Mechanical installation

### 5.1.2 Mounting for standard devices of 0.55 kW or more



[5-2] Mounting for standard devices of 0.55 kW or more

### **Mounting steps**

- 1. Slightly press on the marked spot on the top of the MCI slot cover of the standard device (1).
- 2. Tilt the cover forward and remove it from the standard device (2).
- 3. Loosen the securing screw for the communication module at the standard device (3).
- 4. Insert the communication module into the MCI slot of the standard device (4).
- 5. Tighten the securing screw again (5).

### Installation Mechanical installation

### 5.1.3 Exchanging the communication module



[5-3] Exchanging the communication module

### **Mounting steps**

- 1. Loosen the securing screw for the communication module at the standard device (1).
- 2. Pull the communication module out of the MCI slot of the standard device (2).
- 3. Insert the new communication module into the MCI slot of the standard device (3).
- 4. Tighten the securing screw again (4).

### 5.2 Electrical installation



**Documentation for the standard device, control system, system/machine** Observe the notes and wiring instructions contained in this documentation.

### 5.2.1 Wiring according to EMC guidelines

In typical systems, standard shielding is sufficient for Ethernet cables.

However, in environments with a very high level of interference, EMC resistance can be improved by additionally earthing the cable shield on both sides.

For this observe the following notes:

- 1. Remove the plastic sheath of the cable at a length of 2 cm.
- 2. Fasten the cable shield to the shield support of the standard device.

### 5.2.2 Network topology

It is typical of PROFINET to have a rather free topology the limiting factor of which is large message latencies due to e.g. switches connected in series.

▶ Internal switch latency (□ 20)

The combination of a line and a stub is useful for system wiring.

PROFINET supports the following topologies:

• Switch / star



[5-4] Switch / star topology (S = switch, D = I/O device)

• Tree via switches



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E94YCER007

- [5-5] Tree topology (C =I/O controller, S = switch)
  - Switch / switch



[5-6] Switch/switch topology (S = switch)

### • I/O controller / I/O device



[5-7] Line topology (C = I/O controller, D = I/O device)

### 5.2.3 PROFINET connection

PROFINET is connected via the RJ45 sockets X256 (IN) and X257 (OUT).



#### [5-8] PROFINET connections X256 (IN) and X257 (OUT)

For connection of the communication module to the PROFINET fieldbus, a standard Ethernet patch cable is suitable.

#### ▶ Ethernet cable specification (□ 30)

The installation and removal of the Ethernet cables is optimised for the use of connectors in accordance with the "Automation Initiative of German Domestic Automobile Manufacturers" (AIDA).

### Note!

To prevent the RJ45 socket from being damaged, insert or remove the Ethernet cable connector straight (at a right angle) into or from the socket.

### Pin assignment of the RJ45 sockets





The PROFINET interfaces feature an auto-MDIX function. This function adjusts the polarity of the RJ45 interfaces so that a connection can be established irrespective of the polarity of the opposite PROFINET interface and irrespective of the type of cable used (standard patch cable or crossover cable).

# Installation

**Electrical installation** 

### 5.2.4 Ethernet cable specification

# 1 Note!

Only use cables that meet the listed specifications.

\_\_\_\_\_

Ethernet cable specification	
Ethernet standard	Standard Ethernet (in accordance with IEEE 802.3), 100Base-TX (Fast Ethernet)
Cable type	S/FTP (Screened Foiled Twisted Pair), ISO/IEC 11801 or EN 50173, CAT 5e
Damping	23.2 dB (for 100 MHz and 100 m each)
Crosstalk damping	24 dB (at 100 MHz and per 100 m)
Return loss	10 dB (per 100 m)
Surge impedance	100 Ω

\_\_\_\_\_

### Structure of the Ethernet cable



[5-9] Structure of the Ethernet cable (S/FTP, CAT 5e)

### Colour code of the Ethernet cable

# 1 Note!

Wiring and colour code are standardised in EIA/TIA 568A/568B.

In accordance with the industrial standard, the use of 4-pin Ethernet cables is permissible. The cable type only connects the assigned pins 1, 2, 3 and 6 to one another.



[5-10] Ethernet plug in accordance with EIA/TIA 568A/568B

Pair	Pin	Signal	EIA/TIA 568A	EIA/TIA 568B
3	1	Tx +	White / Green	White / Orange
	2	Tx -	green	orange
2	3	Rx +	White / Orange	White / Green
1	4		blue	blue
	5		White / Blue	Blue / White
2	6	Rx -	orange	green
4	7		White / Brown	White / Brown
	8		brown	brown

### 5.2.5 External voltage supply

The communication module can be externally supplied with voltage via separate supply cables at the 2-pin plug connector **X255**.

# Note!

Always use a separate power supply unit safely separated according to EN 61800-5-1 ("SELV/PELV") in every control cabinet for external voltage supply.

- External voltage supply of the communication module is required if the communication via the bus should be maintained when the supply of the standard device fails.
- Access to parameters of a standard device disconnected from the mains is not possible.

### Wiring of the X255 plug connector

# Stop!

Only wire the plug connector if the standard device is disconnected from the mains.



[5-11] Wiring of the 2-pin plug connector with spring connection

How to wire the plug connector with spring connection:

- 1. Press a screwdriver into the notch below the terminal and keep it pressed.
- 2. Place the supply cable in the terminal.
- 3. Remove the screwdriver from the notch.

### Assignment of the X255 plug connector

Name	Description
+	U = 24 V DC (20.4 V - 0 % 28.8 V + 0 %) I = 140 mA
-	Reference potential for the external voltage supply

\_\_\_\_\_

### Terminal data

Range	Values		
Electrical connection	2-pin plug connector with spring connection		
Possible connections	Rig         0.2 1.5 mm² (AWG 24 16)		
	Without wire end ferrule       0.2 1.5 mm <sup>2</sup> (AWG 24 16)		
	With wire end ferrule, without plastic sleeve 0.2 1.5 mm <sup>2</sup> (AWG 24 16)		
	With wire end ferrule, with plastic sleeve 0.2 1.5 mm <sup>2</sup> (AWG 24 16)		
Stripping length	10 mm		

### 6 Commissioning

During commissioning, system-related data such as motor parameters, operating parameters, responses, and parameters for fieldbus communication are defined for the inverter. For Lenze devices, this is done via the codes.

The codes of the inverter and communication are saved non-volatilely as a data set in the memory module.

In addition, there are codes for diagnosing and monitoring the stations.

▶ <u>Parameter reference</u> (□ 85)

### 6.1 Before initial switch-on



Before switching on the standard device together with the communication module, check the entire wiring for completeness, short-circuit, and earth fault.

# Commissioning

Configuring the PROFINET IO controller

### 6.2 Configuring the PROFINET IO controller

To enable communication with the inverter, you have to configure the IO controller first.

### Configuration for device control

For the configuration of PROFINET, the current PROFINET device description file (XML) of the E84AYCER communication module (PROFINET) has to be imported in the IO controller.

You can find the GSDML-Vx.z-Lenze-8400PNabb-yyyymmdd.xml device description file in the Download area at:

#### www.Lenze.com

Wildcards in the "GSDML-Vx.z-Lenze-8400PN100-yyyymmdd.xml" file name			
х	Main version of the GSDML scheme used		
z	Subversion of the GSDML scheme used		
а	Major version of the software version		
bb	Minor version of the software version		
уууу	Year		
mm	Month		
dd	Day		

### Defining the user data length

The user data length is defined during the initialisation phase of the I/O controller.

The Inverter Drives 8400 support the configuration of max. 16 process data words (max. 32 bytes).

### Description of the device data base file

Selection text	Parameter data (with consistency)	Process data (with consistency)	Assigned I/O memory	
PCD ( <b>n</b> W) AR cons.	-	<b>n</b> words	<b>n</b> words	
n = 1 16 process data words				

### Example of selecting the device data base file

• "PCD (8W) AR cons." = 8 process data words (only in slot 1 of the PROFINET telegram)

A detailed description of consistency is given in the chapter "Consistent parameter data" ( $\Box$  70).
Setting the station name

## 6.3 Setting the station name

## Note!

- The "Node blinking test" PROFINET function by means of which an accessible device can be identified is supported. During execution of the function, the red LED **ME** (Module status displays (1) 74)) blinks.
- Operation on the PROFINET requires a valid station name.
- In the case of impermissible settings, the red **BE** (<u>Fieldbus status displays</u> ((175)) blinks and the error message <u>PROFINET: Station name error [0x01bc6532]</u> ((183) is output. The communication module then continues to work internally with the name deleted.
- If the station name is assigned by the IO controller via PROFINET or the PROFINET configurator of the »Engineer«, changes will be effective immediately.

The station name currently used is shown in code C13864.

The station name ...

- is required for unambiguous addressing of the Inverter Drive 8400 by the I/O controller.
- can either be assigned by the I/O controller via PROFINET or set manually in the »Engineer«.
- has to be allocated in accordance with the PROFINET specification:
  - 1 or several labels separated by ".".
  - Max. length per label: 63 characters
  - Max. total length: 240 characters
  - Permissible characters: [a ... z], [0 ... 9], [.], [-]
  - Labels must not begin or end with [-].
- Prohibited syntax:
  - "n.n.n.n" (n = 0 ... 999)
  - "port-xyz" (x, y, z = 0 ... 9)
  - "port-xyz-abcde" (a, b, c, d, e, x, y, z = 0 ... 9)

In the »Engineer« the station name is set under the Settings tab.

	Settings Monitoring Diagnostics Process data objects Prop	perties
B 8400 HighLine C		
	General	
Actuating drive speed	Station name (C 13899 / 001-008)	000 / 240
		Accept change
	IP address C O . O . O . int	
	Subnetwork mask	
	Gateway address C 0 . 0 . 0 int	

- Then click Accept change. The station name is saved and written to code C13899.
- In the Lenze setting a deleted name is displayed. The name is also deleted if the "Reset to factory defaults" command is executed by an IO supervisor or an I/O controller.

#### How to activate changed settings in the »Engineer«:

- 1. Execute device command C00002 = "11: Save all parameter sets".
- 2. Carry out a "reset node" of the node, <u>or</u> switch the voltage supply of the communication module off and on again

### 6.4 Setting the IP configuration

The IP configuration is required for addressing the Inverter Drive 8400 if communication between the PC/»Engineer« or the IO controller and the inverter is to be established via PROFINET. This requires the allocation of an IP address, subnet mask, and gateway address.

If no PROFINET network or IO controller is available yet, you can allocate the IP address, subnet mask, and gateway address for the communication module by using the following options:

- Settings via the PROFINET configurator of the »Engineer« (1240)
- Setting via codes in the »Engineer« (0 42)



## Note!

- If the IP parameters are assigned by the IO controller via PROFINET or the PROFINET configurator of the »Engineer«, changes become effective immediately and are saved with mains failure protection.
- The assignment of invalid combinations of IP address, subnet mask, and gateway address can have the consequence that no connection to the PROFINET can be established.
- In the case of impermissible settings, the red LED BE (Fieldbus status displays (
   75)) blinks and the error message PROFINET: IP address error [0x01bc6533] (
   84) is output.

Setting the IP configuration

## 6.4.1 Settings via the PROFINET configurator of the »Engineer«

## Note!

- The IP address must only be allocated manually in the »Engineer« if the PROFINET network is not actuated on the IO controller yet (IP address was not allocated by the IO controller yet).
- During the IP parameters are set in the »Engineer«, PROFINET communication with the IO controller must not take place at the same time.
- Changes will be effective immediately and are saved with mains failure protection.
- The parameter values currently used are shown in codes <u>C13010</u> (IP address), <u>C13011</u> (subnet mask), and <u>C13012</u> (gateway address).

How to set the IP parameters via the PROFINET configurator:

1. Execute the menu command **Online** → **Profinet configurator addresses...**.



The **Assign IP addresses** dialog window is opened, and all Lenze PROFINET devices connected are listed.

¢	🛿 Assign IP addresses 🛛 🛛 🔀									
	MAC address	IP address	Subnet mask	Gateway	station name					
	00 0A 86 20 18 5B 00 0A 86 20 15 2B	192.168.254.10 192.168.254.11	255.255.255.0 255.255.255.0	192.168.254.10 192.168.254.11	device2 device1					
	<				>					
	Find device				Close					

2. By double-clicking on the individual IP parameters, you can set the IP configuration for each PROFINET node in the **Configure nodes** dialog window.

🔹 Configure nodes		
MAC address: 00 0A 86 20 15 2B		
IP address: 192.168.254.11		
Subnet mask: 255.255.255.0		
Gateway: 192.168.254.11		
Station name:		
device1		
	Transferred	Cancel

3. Click Transferred.

- The IP configuration is transferred to the corresponding PROFINET node.
- Changes in the IP parameters will become effective immediately.
- The IP parameters are written to codes <u>C13000</u> (IP address), <u>C13001</u> (subnet mask) and <u>C13002</u> (gateway address) of the communication module.



By clicking the **Find device** button in the **Assign IP addresses** dialog window (see step 1), you can check whether the configuration was transferred successfully.

With device command **C00002** = "**11**: **Save all parameter sets**", the current IP configuration is saved non-volatilely in the memory module.

Setting the IP configuration

### 6.4.2 Setting via codes in the »Engineer«

## Note!

- The IP address must only be allocated manually in the »Engineer« if the PROFINET network is not operated on the IO controller yet (IP address has not been allocated by the IO controller yet).
- While setting the IP parameters in the »Engineer«, PROFINET communication with the IO controller must not take place at the same time.
- The parameter values currently used are shown in codes <u>C13010</u> (IP address), <u>C13011</u> (subnet mask), and <u>C13012</u> (gateway address).

In the »Engineer« under the Settings tab you can set the IP parameters manually via code.

	Settings	Monitoring	Diagnostics	Process data objects	Properties
Image: Second system       Image: Second system	Ge	neral			
CAN OnBoard	Statio	on name (C 1	3899 / 001-00	8)	000 / 240
	IP C Sul C Ga C	address 0.0 onetwork ma 0.0 teway addres 0.0	. 0 . 0 sk . 0 . 0 :s . 0 . 0	int int	Accept change

The IP parameters are written to codes <u>C13000</u> (IP address), <u>C13001</u> (subnet mask), and <u>C13002</u> (gateway address).

How to activate changed settings in the »Engineer«:

- 1. Execute the device command C00002 = "11: Save start parameters".
- 2. Carry out a "reset node" of the node, <u>or</u> switch the voltage supply of the communication module off and on again

#### **Decimal representation of the IP parameters**

By clicking the **[ int ]** buttons on the right next to the input fields, the IP parameters are represented as decimal values.

In the case of the decimal representation, the byte sequence is inverted.

Example: IP address 192.168.0.1

• <u>C13000</u> = 16820416 [0000001.0000000.10101000.11000000<sub>bin</sub>]

				By	te 3	;				Byte 2				Byte 1					Byte 0													
1				(	)		168				192																					
0	1	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	1	0	1	0	1	0	0	0	1	1	0	0	0	0	0	0
<u>C13010/4</u> <u>C13010/3</u>					C	130	10/	2					С	130	10/	1																

#### **IP** address

- Valid IP addresses are defined in accordance with RFC 3330.
- The IP address is set/changed in C13000.
- In <u>C13010/1...4</u> the IP address currently used is shown.

## Example: Display of the IP address 192.168.0.1

Code	<u>C13010/1</u>	<u>C13010/2</u>	<u>C13010/3</u>	<u>C13010/4</u>					
Value	192	168	0	1					

#### Subnet Mask

- The subnet mask indicates which part of the IP address is evaluated as net ID or host ID.
- Valid subnet masks are defined in accordance with RFC 1878
- The subnet mask is set/changed in C13001.
- In <u>C13011/1...4</u> the subnet mask currently used is shown.

Example: Display of the subnet mask 255.255.0									
Code	<u>C13011/1</u>	<u>C13011/2</u>	<u>C13011/3</u>	<u>C13011/4</u>					
Value	255	255	255	0					

#### **Gateway address**

- The gateway address is valid if the network address of the IP address and the gateway address are identical.
- If the gateway address and the IP address are identical, gateway functionality is not used.
- DHCP is not supported.
- The gateway address is set/changed in C13002.
- In <u>C13012/1...4</u> the gateway address currently used is shown.

Example: Display of th	Example: Display of the gateway address 192.168.0.1									
Code	<u>C13012/1</u>	<u>C13012/2</u>	<u>C13012/3</u>	<u>C13012/4</u>						
Value	192	168	0	1						

# Commissioning

Establishing an online connection via PROFINET with the Lenze »Engineer«

### 6.5 Establishing an online connection via PROFINET with the Lenze »Engineer«

This functionality is only supported from software version V01.30.05.

## Note!

To ensure perfect operation of cyclic PROFINET communication, online access with the »Engineer« must be effected via a PROFINET switch.

The PROFINET switch integrated in the communication module can execute cyclic PRO-FINET communication prior to normal TCP/IP communication. In the case of PROFINET this is effected via the VLAN identification in the Ethernet frame.



For an online connection between the »Engineer« and the inverter, the inverter must have an IP address (see <u>Setting the IP configuration</u> ((1) 39)).

In the »Engineer« via the menu command **Online** → **Set communication path and go online**, you can select the PROFINET communication path. The PROFINET nodes previously configured are shown in the *Communication path* dialog window:

ŵ	Communication pa	th			
	Device My Axis Project path	Bus connection PROFINET /	Device access path EPL:/192_168_0_10/ y Axis	Type coding E84AFH	Help Please select the required device in the table, specify the bus connection and select the device using the "Find/Enter" button
1	P address	192.168. 0 . 10	2	Search/Enter	
				Accept	Connect Cancel

If the device access path is not configured correctly, the 1 IP address of the inverter selected in the display field can be entered manually here.

Via **2** Search/Enter you can establish a connection to devices which have not appeared in the display field. Corresponding settings for this can be made in the dialog window *Enter IP address*, which is shown:

	🛎 Enter IP Address 🛛 🔀
	Please enter the IP address of the device manually. The automatic search for connected devices is not currently available.
1	IP address: 192.168.254.10 4 Ping
ŧ	Configurator
6	Find OK Cancel

Here you can enter an **3** IP address manually or execute the following actions using the buttons:

- Execute the console command **4** Ping.
- Assign the IP address via the **5** Configurator.
  - ▶ Settings via the PROFINET configurator of the »Engineer« (□ 40)
- Select the device access path to the desired inverter by clicking 6 Find.

After having established the online connection, you can continue work with the »Engineer« as usual. Initial switch-on

### 6.6 Initial switch-on



#### Documentation for the standard device

Observe the safety instructions and information on residual hazards.

# 1 Note!

#### **Establishing communication**

In order to establish communication via an externally supplied communication module, the standard device must be switched on as well.

For further communication of the externally supplied module it is not relevant whether the standard device is switched on or not.

#### Protection against uncontrolled restart

After a fault (e.g. short-term mains failure), it is sometimes undesirable or even impermissible for the drive to restart.

The restart protection is activated in the Lenze setting of the Inverter Drives 8400.

The restart behaviour of the inverter can be set via **C00142** ("auto-start option"):

- C00142 = 9 (Lenze setting)
  - The inverter remains inhibited (even if the fault is no longer active).
  - Bit 0 (inhibit at power-on) and bit 3 (inhibit in the case of undervoltage) are set.
  - The drive restarts in a controlled mode through explicit controller enable: LOW-HIGH edge at digital input X4/RFR.
- C00142 = 8 (Enabled)
  - In order to enable the device directly when switching it on, set bit 0 to zero (FALSE).
  - An uncontrolled restart of the drive is possible.

## 7 Data transfer

PROFINET transmits parameter data, configuration data, diagnostic data, alarm messages, and process data between the host system (IO controller) and the inverters that are part of the fieldbus (I/ O devices). As a function of their time-critical behaviour, the data are transmitted via corresponding communication channels.

#### **Communication channels**

- The process data channel transmits process data.
  - The process data serve to control the inverter.
  - The transmission of process data is time-critical.
  - Process data are transmitted cyclically between the I/O controller and the I/O devices that are part of the fieldbus according to the Provider/Consumer model (continuous exchange of current input and output data).
  - The I/O controller can directly access the process data. In the PLC, for instance, the data are directly assigned to the I/O area.
  - Inverter Drives 8400 allow for a maximum of 16 process data words (16 bits/word) to be exchanged for each direction.
  - Process data are not saved in the inverter.
  - Process data are e.g. setpoints, actual values, control words, and status words.

## Note!

Please observe the direction of the flow of information!

- Process input data (Rx data):
  - Process data from the inverter (IO device) to the IO controller
- Process output data (Tx data):
  - Process data from the IO controller to the inverter (IO device)
- Parameter data are transmitted via the acyclic channel.
  - The transmission of parameter data is usually not time-critical.
  - The access to the parameter data depends on the PROFIdrive profile.
  - Examples of parameter data are operating parameters, motor data, and diagnostic information.
  - The acyclic channel provides access to all Lenze codes.
  - Parameter data changes must be saved via code **C00002** of the Inverter Drives 8400.

Access to process data / PDO mapping

## 8 Process data transfer

### 8.1 Access to process data / PDO mapping

Process data (MCI-PDOs) are transferred via the MCI interface.

- A maximum of 16 words are exchanged per direction.
- The process data are accessed via the port blocks LP\_MciIn and LP\_MciOut. The port blocks are also called process data channels.
- The port block LP\_MciIn maps the received MCI-PDOs.
- The port block LP\_MciOut maps the MCI-PDOs to be sent.
- The port/function block interconnection of the process data objects (PDO) takes place via the Lenze »Engineer«.





#### Software manual / »Engineer« online help for the Inverter Drive 8400

Here you will find detailed information on the port/function block interconnection in the »Engineer« and the port blocks.

\_\_\_\_\_

Preconfigured port interconnection of the process data objects (PDO)



-----

The »Engineer« screenshots shown on the following pages are only <u>examples</u> of the setting sequence and the resulting screens.

\_\_\_\_\_

The data in the display fields may differ from the ones of your project.

### 8.2 Preconfigured port interconnection of the process data objects (PDO)

The preconfigured port interconnection of the process data objects can be activated by setting standard device code **C00007 = "40: MCI"**.

The function block editor (FB Editor) serves to display the port blocks "LP\_MciIn" and "LP\_MciOut" with the preconfigured interconnections:

TO Editor					
🏗 🗭 🖄 🔅 🦫   🕨   100% 💽 🔍	9, 2, 🔢 😑	🔹 🔍 🛛 Layer	I/O interconnection	Editor -	
LS_ParFix 2		LA_NCtrl wCANDriveControl	wDriveControlStatus	I D. Mailluturetata	
wDriveCtrl	LP. Meiln wOtrl	wMCIDriveControl	wStateDetermFailNoLow		LS_DigitalOutput 20
	Er _main.woor	wSMControl	wStateDetermFailNoHigh	LA_NCtrl.bDriveFail	bOut1
LS_ParFree_a 🔞 🕮 nC472_1_a	c	bClnh	bDriveFail (	LS DigitalOutput.bRelay	-0
nC472_2_a	LS_DigitalInput.bClnh	bFailReset	bDriveReady	,	
nC472_3_a	LS_DigitalInput.bln1 @	bSetQuickstop	bCInhActive c	Lá NCtrl nMotorSpeedáct	LS_AnalogOutput 20
nC472_4_a	LP_Mciln.bCtrl_B11	bSetDCBrake	bQSPIsActive		<u>.</u>
		bRFG_Stop	bSpeedCcw		LP_MciOut 20
bCtrl_B8 LA_NCtrl.bRFG_0	LP_Mciln.bCtrl_B8	bRFG_0	bSpeedActCompare	LA_NCtrl.wDriveControlStat	us = bOut2 B0
bCtrl_B11 LA_NCtrl.bSetDCBrake		nVoltageAdd_a	blmaxActive	2	_bOut2 B1
bCtrl_B12		nBoost_a	bSpeedArtEraSet	2	bOut2_B2
bCtrl_B13	4	nTorqueGenLim a	nMotorCurrent a	2	BOut2_B3
bCtrl_B15	C	bSetSpeedCow	nMotorSpeedSet_a	0	bOut2_B4
LA_NCtrl.wMCIDriveContro	LP_Main.bUtrl_B15	6RLQCw	nMotorSpeedAct_a	P LP_MciOut.wOut3	o <sup>bOut2_B5</sup>
bin2_00	Lo_Fairix.birdec	bRLQCcw	nMotorTorqueAct_a	~	o <sup>bOut2_B6</sup>
bln2_B2_	LP Mciln.wln2	nMainSetValue_a	nDCVoltage_a	5	o <sup>bOut2_B7</sup>
bln2_B3	LS_AnalogInput.nln1_a	nAuxSetValue_a	nMotorVoltage_a	>	o <sup>bOut2_B8</sup>
bln2_B4	[	bJogSpeed1			DOut2_B9
bln2_85	6	bJogSpeed2			o <sup>bOut2_B10</sup>
bin2_B6_	c	bJogRamp1			o <sup>DUut2_BII</sup>

Freely configuring the port interconnection of the process data objects (PDO)

8.3 Freely configuring the port interconnection of the process data objects (PDO)

How to freely configure the port interconnection in the »Engineer«:

1. Go to the **Process data objects** tab and click **Go to application**.



2. Go to the **Ports** tab, select the port blocks "MCI\_IN" or "MCI\_OUT" and click **Activate** to activate them.

	Ports Data logger All parameters Pro	perties	
🚊 🧭 PROFINET			
PROFINET	Input ports	Actuating drive speed	Output ports
<u>Actuating drive speed</u>	CAN1_IN		CAN1_OUT
T LAN UnBoard	CAN2_IN •	<ul> <li>(Application)</li> </ul>	<ul> <li>CAN2_OUT</li> </ul>
	CAN3_IN •		CAN3_OUT
	IMCI_IN	•	
			1

#### 3. Click the Change Variable ... button.

S Data log S⊊Rename	ger   All parameters   Prop 🗲 Activate	erties					
Input ports		Actuating drive s	peed	Output	ports		
CAN1_IN CAN2_IN CAN3_IN MCI_IN		(Application)		CAN1 CAN2 CAN3 MCLO			
Mapping		nel	twork def	ault inter	connection		
PROFINET/	MCI_IN_PROFINET : 0	Kno	ot defined>				Network default c <u>h</u> ange
Application	Signal	Tupe	Longth	Index	Opline		
WOBD 1	[not connected]	WOBD	16	C876/1	offline		Change Variable
WORD 2	[not connected]	WORD	16	C876/2	offline		
WORD 3	[not connected]	WORD	16	C876/3	offline		
WORD 4	[not connected]	WORD	16	C876/4	offline		
WORD 5	[not connected]	WORD	16	C876/5	offline		
WORD 6	[not connected]	WORD	16	C876/6	offline		
WORD_7	[not connected]	WORD	16	C876/7	offline		
WORD_8	[not connected]	WORD	16	C876/8	offline		
WORD 9	[not connected]	WORD	16	C876/9	offline	<b>_</b>	

Freely configuring the port interconnection of the process data objects (PDO)

4. Via the \_\_\_\_ button, you can assign signals to the process data words in the Assignment Signal --> Function Block dialog window.



\_\_\_\_\_

Signals for process data words	
. WORD_1 MCI control word (LA_NCtrl)	
+ WORD_2	
WORD_3	e following function block
WORD_4	Akaadu in usa bu
WORD_5	Status word (L.,
WORD_6	Actual speed v Resulting total
WORD_7 In MCI output: Data word 4	
WORD_8  MCI output: Data word 6 MCI output: Data word 7	
WORD_9	
WORD_10  MCI output: Data word 10 MCI output: Data word 11	Ĭ
WORD_11 III MCI output: Data word 12	Ĭ
WORD_12	
WORD_13  CAN control word 16	Fixed value: 0x
WORD_14	· · · · · · · · · · · · · · · · · · ·
WORD_15	
WORD_16	ncel OK
E	Close

Freely configuring the port interconnection of the process data objects (PDO)

Moreover you can assign signals to the individual control and status bits at the WORD\_1 and WORD\_2 process data words via the 📑 and 🛄 buttons.



Freely configuring the port interconnection of the process data objects (PDO)

-``@\_\_\_\_\_\_ Tip!

When the port blocks "LP\_MciIn" and "LP\_MciOut" are activated (see 1.), they will be visible in the FB Editor. Here you can also assign signals to the process data words.

\_\_\_\_\_

FB Editor					
🎀 🚰 😤 🌮 🕨 🛛 100% 🔹 🔍 G	R 🔒 🔜 😑	- 🔍 Layer	I/O interconnection	Editor	
LS_ParFix 12 bTrue		LA NCtrl wCANDriveControl	wDriveControlStatus	<ul> <li>LP_MciOut.wState</li> </ul>	
wDriveCtrl	LP_Mciln.wCtrl •	wMCIDriveControl	wStateDetermFailNoLow	LA_NCtrl.bDriveFail	LS_DigitalOutput [2][[] DRelay
	• • • • • • • • •	wSMControl	wStateDetermFailNoHigh	-	bOut1
nC472_1_a	c	bClnh	bDriveFail	LS_DigitalOutput.bRelay	
nC472_2_a	LS_DigitalInput.bClnh	bFailReset	bDriveReady	o]	
nC472_3_a	LS_DigitalInput.bln1	bSetQuickstop	bClnhActive	LA_NCtrl.nMotorSpeedAct_	_a o <sup>nOut1V_a</sup>
nC472_4_a	LP_Mciln.bCtrl_B11	bSetDCBrake	bQSPIsActive	D	
		bRFG_Stop	bSpeedCcw	•	LP_MciOut 2
bCtrl_B8	LP_Mciln.bCtrl_B8	bRFG_0	bSpeedActCompare	LA_NCtrl.wDriveControlSta	tus = bOut2 B0
bCtrl_B11		nVoltageAdd_a	bimaxActive	D	_bOut2 B1
bCtrl_B12		nBoost_a	bSpeedSetReached		bOut2_B2
bCtrl_B13		nTorqueMotum_a	ntdeterCurrent a	0	bOut2_B3
bCtrl_B15	L(	hSetSpeedCov	nMotorCorrent_a	o I	bOut2_B4
WCtrl - LA_NCtrl.wMClDriveControl	LP_Mciln.bCtrl_B15	bBLOOw	nMotorSpeedóct_a	P LP_MciOut.wOut3	_bOut2_B5
bln2_B0	LS_ParFix.bTrue	hBLQCow	nMotorTorqueAct_a	°	bOut2_B6
bin2_B1		nMainSetValue a	nDCVoltage a	0	_ _bOut2_B7
bin2_B2	LP_Mailn.win2 9	nAuxSetValue_a	nMotorVoltage_a	0	bOut2_B8
	.s_Analoginput.nin1_a G	bJogSpeed1		0	bOut2_B9
bin2_64 bin2_85	Le 17	bJogSpeed2			bOut2_B10
bin2_00 bin2_B6_		bJogRamp1			o <sup>bOut2_B11</sup>

The acyclic channel (PROFIdrive profile)

## 9 Parameter data transfer

### 9.1 The acyclic channel (PROFIdrive profile)

An optional service extension is the acyclic parameter data transfer. Cyclic and acyclic PROFINET services can be operated simultaneously in the network.

#### **Product features**

- There is always only one parameter request in process (no pipelining).
- No spontaneous messages are transferred.
- There are only acyclic parameter requests.
- Profile-specific parameters can be read independently of the I/O device state.

#### 9.1.1 Connection establishment of an I/O controller to an I/O device

An I/O controller can always be used to request parameters from an I/O device if the I/O device is in the "DATA\_EXCHANGE" state.



[9-1] Data communication via the acyclic channel

The acyclic channel (PROFIdrive profile)

## 9.1.2 Acyclic data transmission process



[9-2] Data communication via the acyclic channel

- A "Write.req" is used to transmit the data set (DB47) in the form of a parameter request to the I/O device.
- "Write.res" confirms the receipt of the message by the I/O controller.
- The I/O controller requests the response of the I/O device with "Read.req".
- The I/O device responds with a "Read.res (-)" if processing is not yet completed.
- After parameter processing, the parameter request is completed by transmitting the parameter response in the form of a "Read.res (+)" to the I/O controller.

The acyclic channel (PROFIdrive profile)

### 9.1.3 Structure of the PROFINET data frame

Des <sup>.</sup> Add	: Scr Addr	VLAN Day	Туре 0800Н	RPC	NDR	Read/Write Block	Data	FSC
6 byte	s 6 bytes	4 bytes	4 bytes	80 bytes	64 bytes	64 bytes	0 240 bytes	4 bytes

[9-3] PROFINET data telegram

In the "Read/Write Block", the initiator specifies the access to data set "DB47". The data which are written to this index or read by it contain a header and the parameter request or the parameter response. The read data or the data to be written are contained in the "Data" field.

The following subchapters describe the parameter request and the parameter response in detail.

## **PROFINET** specification

Here you will find detailed information on the PROFINET data telegram.

#### Assignment of the user data depending on the data type

Depending on the data type used, the user data are assigned as follows:

Data type	Length	User data assignment					
		Byte 1	Byte 2	Byte 3	Byte 4	Byte	
String	x bytes						
U8	1 byte		00				
U16	2 bytes	High byte	Low byte				
U32	4 bytes	High	word	Low word			
		High byte	Low byte	High byte	Low byte		

Reading parameters from the inverter

### 9.2 Reading parameters from the inverter

## 1 Note!

- When a read request is processed, no parameter value is written to the I/O device.
- In the case of a multi-parameter read request, parameter attribute, index, and subindex are repeated "n" times, "n" being the number of parameters requested.

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#### **Request header**

Byte 1	Byte 2	Byte 3	Byte 4
Request reference	Request identification	Axis	Number of indices

Field	Data type	Values
Request reference	U8	This value is specified by the I/O controller.
Request identification	U8	0x01: Request parameters for reading
Axis	U8	0x00 or 0x01
Number of indices	U8	0x"n" (n = number of parameters requested)

#### **Parameter attribute**

Byte 5	Byte 6
Attribute	Number of subindices

Field	Data type	Values
Attribute	U8	0x10: Value
Number of subindices	U8	0x00 or 0x01

#### Index and subindex

Byte 7	Byte 8	Byte 9	Byte 10	
Index		Subindex		
High byte	Low byte	High byte	Low byte	

Field	Data type	Values
Index	U16	0x0001 0xFFFF (1 65535)
Subindex	U16	0x0001 0xFFFF (1 65535)

Reading parameters from the inverter

### 9.2.1 Response to a correctly executed read request

## 1 Note!

• Responses to read requests do not contain parameter attributes and indices/subindices.

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• When a multi-parameter read request is transmitted, the parameter format and the parameter value are repeated "n" times, "n" being the number of parameters requested.

#### **Response header**

Byte 1	Byte 2	Byte 3	Byte 4
Request reference (mirrored)	Response identification	Axis (mirrored)	Number of indices

Field	Data type	Values
Request reference	U8	Mirrored value of the parameter request
Response identification	U8	0x01: Parameter has been read
Axis	U8	0x00 or 0x01
Number of indices	U8	0x"n" (n = number of parameters requested)

#### **Parameter format**

Byte 5	Byte 6
Format	Number of values

Field	Data type	Values
Format	U8	0x02: Integer8 0x03: Integer16 0x04: Integer32 0x05: Unsigned8 0x06: Unsigned16 0x07: Unsigned32 0x09: Visible string 0x0A: Octet string 0x40: Zero 0x41: Byte 0x42: Word 0x43: Double word
Number of values	U8	<ul> <li>0x01</li> <li>Number of requested subindices. (If there is more than one subindex, only the parameter value is repeated.)</li> <li>In the case of string codes, the number of characters is entered here.</li> </ul>

Reading parameters from the inverter

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#### Parameter value

Byte 7	Byte 8	Byte 9	Byte 10
Value			

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Field	Data type	Values
Value	String	Any
	U8	0x00 0xFF
	U16	0x0000 0xFFFF
	U32	0x0000 0000 0xFFFF FFFF

## 9.2.2 Response to a read error

#### **Response header**

Byte 1	Byte 2	Byte 3	Byte 4
Request reference (mirrored)	Response identification	Axis (mirrored)	Number of indices

Field	Data type	Values
Request reference	U8	Mirrored value of the parameter request
Response identification	U8	0x81: Parameter has not been read • The data in the bytes 7 + 8 must be interpreted as an error code.
Axis	U8	0x00 or 0x01
Number of indices	U8	0x"n" (n = number of parameters requested)

#### **Parameter format**

Byte 5	Byte 6
Format	Number of values

Field	Data type	Values
Format	U8	0x44: Error
Number of values	U8	0x01: Error code without additional information 0x02: Error code with additional information

Reading parameters from the inverter

#### Error code

Byte 7	Byte 8	Byte 9	Byte 10
Error code		Additional information (if available)	
High byte	Low byte	High byte	Low byte

Field	Data type	Values
Error code	U16	0x0000 0xFFFF • <u>Error information (error)</u> (🖽 68)
Additional information (if available)	U16	

#### 9.2.3 Frame example: Read request

The heatsink temperature of the inverter is to be read.

- Code to be read: C00061
- Heatsink temperature: 43 °C

#### **Parameter request**

Byte 1	Byte 2	Byte 3	Byte 4
Request reference	Request identification	Axis	Number of indices
0xXX	0x01	0x00	0x01
	Request parameters for reading		

Byte 5	Byte 6
Attribute	Number of subindices
0x10	0x00
Value	No subindex

Byte 7	Byte 8	Byte 9	Byte 10
Index		Subindex	
High byte	Low byte	High byte	Low byte
0x5F	0xC2	0x00	0x00
Index = 24575 - code no. = 24575 - 6	1 = 24514 = 0x5F C2	No subindex	

Reading parameters from the inverter

#### Parameter response to a correctly executed read request

Byte 1	Byte 2	Byte 3	Byte 4
Request reference	Response identification	Axis	Number of indices
0xXX	0x01	0x00	0x01
(mirrored)	Parameter has been read	(mirrored)	

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Byte 5	Byte 6
Format	Number of values
0x43	0x01
Double word	1 value

Byte 7	Byte 8	Byte 9	Byte 10
Value			
High word: high byte	High word: low byte	Low- word: high byte	Low word: low byte
0x00	0x00	0x00	0x2B
Read value = 0x00 00 00 2B = 43 x 1 (internal factor) = 43 [°C]			

#### Parameter response to a read error

Byte 1	Byte 2	Byte 3	Byte 4
Request reference	Response identification	Axis	Number of indices
0xXX	0x81	0x00	0x01
(mirrored)	Parameters not read	(mirrored)	

Byte 5	Byte 6
Format	Number of values
0x44	0x01
Error	Error code without additional infor- mation

Byte 7	Byte 8	
Error code		
High byte	Low byte	
For the meaning see the chapter " <u>Error information</u> ( <u>error</u> )" ([1] 68)		

Writing parameters to the inverter

### 9.3 Writing parameters to the inverter

## Note!

- When a multi-parameter write request is processed, the parameter attribute, index, subindex, and then the parameter format and parameter value are repeated "n" times, "n" being the number of parameters requested.
- A parameter request must not exceed the maximum data length of 240 bytes.

#### **Request header**

Byte 1	Byte 2	Byte 3	Byte 4
Request reference	Request identification	Axis	Number of indices

Field	Data type	Values
Request reference	U8	This value is specified by the I/O controller.
Request identification	U8	0x02: Write parameter
Axis	U8	0x00 or 0x01
Number of indices	U8	0x"n" (n = number of parameters requested)

#### **Parameter attribute**

Byte 5	Byte 6
Attribute	Number of subindices

Field	Data type	Values
Attribute	U8	0x10: Value
Number of subindices	U8	0x00 or 0x01

#### Index and subindex

Byte 7	Byte 8	Byte 9	Byte 10
Index		Subindex	
High byte	Low byte	High byte	Low byte

Field	Data type	Values
Index	U16	0x0001 0xFFFF (1 65535)
Subindex	U16	0x0001 0xFFFF (1 65535)

Writing parameters to the inverter

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#### **Parameter format**

Byte 11	Byte 12
Format	Number of values

Field	Data type	Values
Format	U8	0x02: Integer8 0x03: Integer16 0x04: Integer32 0x05: Unsigned8 0x06: Unsigned16 0x07: Unsigned32 0x09: Visible string 0x0A: Octet string 0x40: Zero 0x41: Byte 0x42: Word 0x43: Double word
Number of values	U8	<ul> <li>0x01</li> <li>Number of requested subindices. (If there is more than one subindex, only the parameter value is repeated.)</li> <li>In the case of string codes, the number of characters is entered here.</li> </ul>

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#### Parameter value

Byte 13	Byte 14	Byte 15	Byte 16
Value			

Field	Data type	Values
Value	String	Any
	U8	0x00 0xFF
	U16	0x0000 0xFFFF
	U32	0x0000 0000 0xFFFF FFFF

Writing parameters to the inverter

### 9.3.1 Response to a correctly executed write request

#### **Response header**

Byte 1	Byte 2	Byte 3	Byte 4
Request reference (mirrored)	Response identification	Axis (mirrored)	Number of indices

Field	Data type	Values
Request reference	U8	Mirrored value of the parameter request
Response identification	U8	0x01: Parameter written
Axis	U8	0x00 or 0x01
Number of indices	U8	0x"n" (n = number of parameters requested)

#### 9.3.2 Response to a write error

## 1 Note!

In the case of a multi-parameter request, correct and possible faulty messages are summarised in one frame. They have the following data contents:

- Correct message
  - Format: 0x40
  - Number of values: 0x00
- Faulty message
  - Format: 0x44
  - Number of values: 0x01 or 0x02
  - Error code without additional information (number of values = 0x01) or
  - Error code with additional information (number of values = 0x02)

A faulty access to a parameter "n" is indicated at the nth position in the response frame of a multi-parameter request.

## Writing parameters to the inverter

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#### **Response header**

Byte 1	Byte 2	Byte 3	Byte 4
Request reference	Response identification	Axis	Number of indices
(mirrored)		(mirrored)	

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Field	Data type	Values
Request reference	U8	Mirrored value of the parameter request
Response identification	U8	0x82: Parameter has not been written • The data in the bytes 7 + 8 must be interpreted as an error code.
Axis	U8	0x00 or 0x01
Number of indices	U8	0x"n" (n = number of parameters requested)

#### **Parameter format**

Byte 5	Byte 6
Format	Number of values

Field	Data type	Values
Format	U8	0x44: Error
Number of values	U8	0x01: Error code without additional information 0x02: Error code with additional information

#### Error code

Byte 7	Byte 8	Byte 9	Byte 10
Error code		Additional information (if available)	
High byte	Low byte	High byte	Low byte

Field	Data type	Values
Error code	U16	0x0000 0xFFFF ▶ <u>Error information (error)</u> (□ 68)
Additional information (if available)	U16	

Writing parameters to the inverter

## 9.3.3 Frame example: Write request

In the inverter, the deceleration time for quick stop is to be set to 50 ms.

• Code to be written: C00105

#### **Parameter request**

Byte 1 Byte 2		Byte 3	Byte 4
Request reference	st reference Request identification		Number of indices
0xXX 0x02		0x00	0x01
	Write parameters	Axis 0	1 index

Byte 5	Byte 6
Attribute	Number of subindices
0x10	0x00
Value	No subindex

Byte 7	Byte 8	Byte 9	Byte 10
Index		Subindex	
High byte	Low byte	High byte	Low byte
0x5F	0x96	0x00	0x00
Index = 24575 - code no. = 24575 - 105 = 24470 = 0x5F 96		No subindex	

Byte 11	Byte 12
Format	Number of values
0x43	0x01
Double word	1 value

Byte 13	Byte 14	Byte 15	Byte 16
Value			
High word: high byte	High word: low byte	Low- word: high byte	Low word: low byte
0x00	0x00	0x00	0x32
Value to be written = 0.05 [s] x 1000 (internal factor) = 50 = 0x00 00 00 32			

Writing parameters to the inverter

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#### Parameter response to a correctly executed write request

Byte 1	Byte 2	Byte 3	Byte 4
Request reference	Response identification	Axis	Number of indices
0xXX	0x02	0x00	0x01
(mirrored)	Parameter has been written	(mirrored)	1 index

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#### Parameter response after write error

Byte 1 Byte 2		Byte 3	Byte 4	
Request reference	Response identification	Axis	Number of indices	
0xXX	0x82	0x00	0x01	
(mirrored)	Parameter has not been written	(mirrored)	1 index	

Byte 5	Byte 6
Format	Number of values
0x44	0x01
Error	Error code without additional infor- mation

Byte 7	Byte 8
Error code	
High byte	Low byte
For the meaning see the chapter " <u>Error information</u> (error)" (	

Error information (error)

## 9.4 Error information (error)

Error code	Meaning	Description	Additional in- formation
0x0000	Impermissible parameter number	Access to unavailable parameter	-
0x0001	Parameter value cannot be changed	Change access to a parameter value that cannot be changed	Subindex
0x0002	Lower or upper value limit ex- ceeded	Change access with value beyond the value limits	Subindex
0x0003	Faulty subindex	Access to unavailable subindex	Subindex
0x0004	No array	Access with subindex to non-indicated parameter	-
0x0005	Wrong data type	Change access with value that does not match the data type of the parameter	-
0x0006	No setting permitted (only resettable)	Change access with value unequal to 0 where this is not permitted	Subindex
0x0007	Description element cannot be changed	Change access to a description element that cannot be changed	Subindex
0x0008	Reserved	(PROFIdrive profile V2: PPO-Write requested in the IR is not available)	-
0x0009	Description data not availab- le	Access to unavailable description (parameter value is available)	-
0x000A	Reserved	(PROFIdrive profile V2: Wrong access group)	-
0x000B	No parameter change rights	Change access without parameter change rights	-
0x000C	Reserved	(PROFIdrive profile V2: Wrong password)	-
0x000D	Reserved	(PROFIdrive profile V2: Text in the cyclic traffic can- not be read)	-
0x000E	Reserved	(PROFIdrive profile V2: Name in the cyclic traffic can- not be read)	-
0x000F	No text array available	Access to unavailable text array (parameter value is available)	-
0x0010	Reserved	(PROFIdrive profile V2: Missing PPO-Write)	-
0x0011	Request cannot be executed due to the operating state	Access is not possible due to temporary reasons not specified here	-
0x0012	Reserved	(PROFIdrive profile V2: Other error)	-
0x0013	Reserved	(PROFIdrive profile V2: date in the cyclic traffic can- not be read)	-
0x0014	Value impermissible	Change access with the value that is inside the value limits but not permissible for other permanent re- asons (parameters with defined individual values)	Subindex
0x0015	Response too long	The length of the current response exceeds the maxi- mum transmittable length	-
0x0016	Parameter address imper- missible	Impermissible or non-supported value for attribute, number of subindices, parameter number, or subin- dex, or a combination	-
0x0017	Format impermissible	Write request: Impermissible or non-supported for- mat of parameter data	-
0x0018	Number of values not consis- tent	Write request: Number of values of the parameter data do not match the number of subindices in the parameter address	-
0x0019	Reserved	-	-
0x0064			

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Error information (error)

Error code	Meaning	Description	Additional in- formation
0x0065	Manufacturer-specific	-	-
0x00FF			

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Consistent parameter data

### 9.5 Consistent parameter data

In the PROFINET communication system, data are permanently exchanged between the host (CPU + I/O controller) and the standard device via the plugged-on I/O device interface module. The I/O controller and the CPU (central processing unit) of the host access a joint memory: the dual port memory (DPM).

• The DPM permits a data exchange in both directions (write/read):



It could happen that a slower I/O controller writing would be overtaken by a faster CPU reading within a cycle time without any further data organisation.

In order to avoid such an impermissible state, the parameter data to be transmitted must be marked as "consistent".

#### Data communication with consistent data

With consistency, either "reading" or "writing" is possible when the I/O controller and the CPU simultaneously access the memory:

- The I/O controller transfers data only as a complete data set.
- The CPU can only access completely updated data sets.
- The I/O controller cannot read or write data as long as the CPU accesses consistent data.

The result becomes clear from the example below:



- 1. As the I/O controller can only write when the CPU does not read, the I/O controller has to wait until the data are completely read by the CPU.
- 2. The I/O controller only writes a complete data set into the DPM.

#### Configuring consistent data

## Note!

Consistency is achieved by an appropriate I/O controller configuration (see documentation for the configuring software).

## 10 Monitoring

### 10.1 Interruption of PROFINET communication

An interruption of PROFINET communication in the "Data\_Exchange" state, e.g. by cable break or failure of the I/O controller is recognised by the I/O device.



1. During the initialisation of PROFINET communication the watchdog monitoring time specified in the I/O controller (<u>C13882</u>) is transferred to the I/O device.

If the I/O device does not receive any valid process data in the "Data\_Exchange" state, the process data are treated according to the setting in 2 <u>C13885</u>. (Like this the data that were sent last by the I/O controller can be used or set to zero.)

After the watchdog monitoring time has elapsed, the I/O device changes to the "No\_Data\_Exchange" status (see <u>C13861</u>), and the red LED **BE** is activated (<u>Fieldbus status</u> <u>displays</u> (<u>C175</u>)).

There is no response in the I/O device.

 To trigger a response in the IO device, you additionally have to set a Response of the Inverter Drive 8400 1 (C13880) under the Monitoring tab in the »Engineer«.

B-1 8400_PROFINET	Settings Monitoring Diagnostics Process data objects		
🖻 🙀 8400 HighLine C			
	General		
	Monitoring "Watebdog /Data Evolvange"		
CAN OpBoard			
MDXMA-071-12 (Y)			
	Delete process data		
	2 C PDOs set to '0'		
	Time monitoring		
	Reaction time delay		
	3 C 65535		

By setting a **Reaction time delay 3** (<u>C13881</u>) you can decelerate this response.

- In the Lenze setting "0 ms", this monitoring is activated.
- With the setting "65535 ms", this monitoring is deactivated.
- A change of monitoring will be effective immediately.
- The monitoring time elapses when the "Data\_Exchange" status is exited.

After this response delay has elapsed, the response set is executed with the error message "<u>PROFINET: Data\_Exchange status quit [0x01bc6531]</u>" (<u>Careford</u> 83).

### 10.2 Interruption of internal communication

- The response in the event of a communication error between the communication module and the Inverter Drive 8400 can be set via code **C01501**.
- The communication module reports a connection interruption to the IO controller and changes to the "No\_Data\_Exchange" state.

• The error message "<u>PROFINET: Exist. conn. to 8400 lost [0x01bc3100]</u>" (🖽 81) is output.

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## **11** Diagnostics

For purposes of fault diagnostics, the communication module is provided with the LEDs on the front. Furthermore you can carry out the <u>Diagnostics with the »Engineer«</u> (**II** 77).

## **11.1** LED status displays



## Note!

During normal operation ...

- only the LEDs MS ([] 74) and BS ([] 75) should be lit permanently.
- the green LEDs on the RJ45 sockets X256/X257 must be lit or blinking ([] 76).

The following status displays are distinguished:

- Module status displays (III 74)
- Fieldbus status displays (III 75)
- Status displays at X256 and X257 (III 76)

## **11.1.1** Module status displays

The LEDs **MS**, **ME** and **DE** indicate the module status.



LED	Colour	Status	Description
MS	green	On	
			The communication module is supplied with voltage and is connec- ted to the standard device.
		blinking	200 ms
			The communication module is supplied with voltage, but is not con- nected to the standard device. (Standard device is switched off, in the initialisation phase, or not available.)
ME	red	On	
			An error has occurred in the communication module.
		blinking	200 ms
			The "Node blinking test" PROFINET function is activated by the I/O controller. The blinking LED serves to identify/localise accessible I/O devices.
EN	red	On	
			The communication module is not accepted by the basic device or the basic device is not active (see notes in the documentation rela- ting to the basic device.)

# Diagnostics LED status displays

## **11.1.2** Fieldbus status displays

The LEDs **BS** and **BE** indicate the fieldbus status.



LED	Colour	Status	Description
BS	green	Off	The communication module is not active on the fieldbus or is in the INIT state.
		blinking	200 ms 200 ms The communication module is in the DATA _EXCHANGE status.
BE	red	On	Bus error/fault is active (e.g. Ethernet cable not connected). The com- munication module is in the NO_DATA_EXCHANGE status.
		blinking	200 ms 200 ms Impermissible settings: • Invalid station name • Invalid IP parameters The communication module has been initialised and continues to work internally with the respective standard values.

## 11.1.3 Status displays at X256 and X257

The LEDs below the RJ45 sockets X256 and X257 indicate the PROFINET connection status.



LED	Colour	Status	Description
А	green	Off	No connection to PROFINET
		On	
			Connection to PROFINET has been established.
В	Yellow	Off	No communication
		On <i>or</i> Flickers	50 ms
			Communication active

## **11.2** Diagnostics with the »Engineer«

In the »Engineer« under the **Diagnostics** tab, you will find PROFINET diagnostics information.

B400_PROFINET B400 HighLine C PROFINET CALUATING drive speed CAN OnBoard MDXMA-071-12 (Y)	Settings Monitoring Di	iagnostics Process data C 13864 / 001-008)	objects Properties
	Address MAC ID: Station C 00 MAC ID: Port1 C 00 MAC ID: Port2 C 00		Profinet diagnostics Bus status C 0x0 Bus error C 0 Data cycles per second C 0 Read cycles per second C 0 Write cycles per second C 0 Write cycles per second C 0 Display: Most recent PRM data C 00 Display: Most recent diagnostic data C 00
	Process	is data	Module information

## 11.3 Diagnostic data

• The I/O device sends an alarm message to the I/O controller to signalise the diagnostic data below.

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- Errors and warnings of the Inverter Drive 8400 and the module connected to it are sent to the IO controller as extended diagnostic messages.
- With code <u>C13887</u>, the transmission of an alarm message can be suppressed for specific error messages.
- The diagnostic data can be displayed using the hexadecimal representation of the Siemens S7 engineering tool.

Bytes	Meaning	Value [hex]
16	Diag. block header	0x0010 001C 0100
7 8	Alarm type	0x0001 (diagnosis)
9 12	API	0x0000 0000
13, 14	Slot number	0x0001/0x0002
15, 16	Subslot number	0x0001
17 20	Module ID	ID according to module
21 24	Submodule ID	ID according to module
25, 26	Alarm specifier	0xB000
27, 28	User structure identifier	0x0001
29 32	Error code of the Inverter Drive 8400 / E84AYCER	

## Error code of Inverter Drive 8400



- The error code can be found in bytes 29 ... 32 of the diagnostic message.
- In the logbook and in code **C00165**, the error number is shown in the following syntax in order to facilitate the readability:

[error type].[error subject area no.].[error ID]

Example: error message "PROFINET: Data\_Exchange status quit [0x01bc6531]"

			Byte	32				Byte 31							Byte 30								Byte 29								
			0x0	)1							0х	bc							0x	65							0х	31			
0	0	0	0	0	0	0	1	1	0	1	1	1	1	0	0	0	1	1	0	0	1	0	1	0	0	1	1	0	0	0	1
Resp	Response Instance ID Module ID															Erro	or ID														

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Software manual/»Engineer« online help for Inverter Drive 8400

Detailed information on the error codes is provided here.

## **Error messages**

Short overview of the PROFINET error messages

sages.

## 12 Error messages

[ALinkKeywords] Error messages This chapter supplements the error list in the software manual and the »Engineer« online help for the Inverter Drive 8400 by the error messages of the communication module.



Software manual/»Engineer« online help for Inverter Drive 8400 Here you will find general information on diagnostics & fault analysis and on error mes-

[Search-Keywords] Error messages

### 12.1 Short overview of the PROFINET error messages

The following table contains all PROFINET error messages in numerical order of the error number. Furthermore the preset error response and - if applicable – the parameter for setting the error response is specified.



If you click on the cross-reference in the first column, you will get a detailed description (causes and remedies) of the corresponding error message.

Error no. [hex]	Subject area no. [dec]	Error no. [dec]	Error text	Error type (Error response)	Adjustable in
<u>0x01bc3100</u>	444	12544	PROFINET: Exist. connect. to 8400 lost	1: No Response	-
<u>0x01bc5531</u>	444	21809	PROFINET: Memory: No access	1: No Response	-
<u>0x01bc5532</u>	444	21810	PROFINET: Memory: Read error	1: No Response	-
0x01bc5533	444	21811	PROFINET: Memory: Write error	1: No Response	
0x01bc6010	444	24592	PROFINET: Restart by watchdog reset	1: No Response	
<u>0x01bc6011</u>	444	24593	PROFINET: Internal error	1: No Response	-
0x01bc6100	444	24832	PROFINET: Internal error	1: No Response	
0x01bc6101	444	24833	PROFINET: Internal error	1: No Response	
<u>0x01bc641f</u>	444	25631	PROFINET: Invalid parameter set	1: No Response	-
0x01bc6420	444	25632	PROFINET: Error: Lenze setting loaded	1: No Response	-
<u>0x01bc6430</u>	444	25648	PROFINET: Invalid module configuration	1: No Response	-
<u>0x01bc6501</u>	444	25857	PROFINET: Record parameter: Invalid read	4: Warning locked	-
0x01bc6502	444	25858	PROFINET: Record parameter: Invalid write	4: Warning locked	-
<u>0x01bc6503</u>	444	25859	PROFINET: Data output status bad	4: Warning locked	-
<u>0x01bc6531</u>	444	25905	PROFINET: Data_Exchange status quit	0: None	<u>C13880/1</u>
0x01bc6532	444	25906	PROFINET: Station name error	1: No Response	
0x01bc6533	444	25907	PROFINET: IIP address error	1: No Response	•
0x01bc6534	444	25908	PROFINET: Stack init error	1: No Response	•
0x01bc6650	444	26192	PROFINET: Internal error	1: No Response	-

## 12.2 Possible causes and remedies

In this chapter, all error messages of the communication module are listed in numerical order of the error numbers. Possible causes and remedies and responses to the error messages are described in detail.

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You will find a list of all error messages of the communication module in alphabetical order in the previous chapter "<u>Short overview of the PROFINET error messages</u>" (**(1** 80).

#### PROFINET: Exist. conn. to 8400 lost [0x01bc3100]

Response (Lenze setting printed in bold)	Setting: not possible				
□ No reaction □ System fault	uble 🗆 WarningLocked 🗆 Warning 🗅 Information				
Cause	Remedy				
<ul> <li>MCI communication to Inverter Drive 8400 is interrupted.</li> <li>Inverter Drive 8400 is switched off.</li> <li>The communication module is not connected correctly at the MCI slot of the Inverter Drive 8400.</li> </ul>	<ul> <li>Switch on Inverter Drive 8400.</li> <li>Check screwed connection of the communication module at the MCI slot of the Inverter Drive 8400.</li> <li>Send the communication module and Inverter Drive 8400 together with a description of the fault to Lenze.</li> </ul>				

#### PROFINET: Memory: No access [0x01bc5531]

Response (Lenze setting printed in bold)	Setting: not possible							
□ No reaction □ System fault	uble 🗆 WarningLocked 🗆 Warning 🗆 Information							
Cause	Remedy							

#### PROFINET: Memory: Read error [0x01bc5532]

Response (Lenze setting printed in bold)	Setting: not possible						
□ No reaction □ System fault	ble 🗆 WarningLocked 🗆 Warning 🗆 Information						
Cause	Remedy						

#### PROFINET: Memory: Write error [0x01bc5533]

Response (Lenze setting printed in bold)	Setting: not possible						
□ No reaction □ System fault	uble 🗆 WarningLocked 🗆 Warning 🗆 Information						
Cause	Remedy						

### PROFINET: Restart by watchdog reset [0x01bc6010]

Response (Lenze setting printed in bold)	Setting: not possible						
□ No reaction □ System fault	uble 🗆 WarningLocked 🗆 Warning 🗆 Information						
Cause	Remedy						

#### PROFINET: Internal error [0x01bc6011]

Response (Lenze setting printed in bold)	Setting: not possible
□ No reaction □ System fault 🗵 Fault □ Trouble □ Quick stop by trouble □ WarningLocked □ Warning □ Information	
Cause	Remedy

#### PROFINET: Internal error [0x01bc6100]

Response (Lenze setting printed in bold)	Setting: not possible
□ No reaction □ System fault ☑ Fault □ Trouble □ Quick stop by trouble □ WarningLocked □ Warning □ Information	
Cause	Pemedy
cusc	Keineuy

#### PROFINET: Internal error [0x01bc6101]

Response (Lenze setting printed in bold)	Setting: not possible
□ No reaction □ System fault	
Cause	Remedy
Internal error	Send communication module together with a descripti- on of the fault to Lenze.

#### PROFINET: Invalid parameter set [0x01bc641f]

Response (Lenze setting printed in bold)	Setting: not possible
□ No reaction □ System fault I Fault □ Trouble □ Quick stop by trouble □ WarningLocked □ Warning □ Information	
Cause	Remedy
No active parameter set could be loaded.	<ul> <li>Download application again (including module).</li> <li>Send communication module together with a description of the fault to Lenze.</li> </ul>

#### PROFINET: Error: Lenze setting loaded [0x01bc6420]

Response (Lenze setting printed in bold)	Setting: not possible
□ No reaction □ System fault ☑ Fault □ Trouble □ Quick stop by trouble □ WarningLocked □ Warning □ Information	
C	
Cause	Remedy

### PROFINET: Invalid module configuration [0x01bc6430]

Response (Lenze setting printed in bold)	Setting: not possible	
□ No reaction □ System fault		
Cause	Remedy	

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### PROFINET: Record Parameter: Invalid read [0x01bc6501]

Response (Lenze setting printed in bold)	Setting: not possible
□ None □ System fault □ Fault □ Trouble □ Quick stop by trouble 🗵 Warning locked □ Warning □ Information	
Cause	Remedy

#### PROFINET: Record Parameter: Invalid write [0x01bc6502]

Response (Lenze setting printed in bold)	Setting: not possible
□ None □ System fault □ Fault □ Trouble □ Quick stop by trouble 🗵	Warning locked UWarning Information
Cause	Remedy
Invalid parameter write access When reading back the data, the IO Controller has re- quested a data length (number of data bytes) that is to small.	Check configuration.

#### PROFINET: Data output status bad [0x01bc6503]

Response (Lenze setting printed in bold)	Setting: not possible
□ None □ System fault □ Fault □ Trouble □ Quick stop by trouble <b>Ⅳ Warning locked</b> □ Warning □ Information	
Cause	Remedy
Output data invalid.     Connection to Siemens S7 has been interrupted	Check cables and terminals.     Connect network cable to PROFINET connections

#### PROFINET: Data\_Exchange status quit [0x01bc6531]

Response (Lenze setting printed in bold)	Setting: <u>C13880/1</u> (☑ Adjustable response)
⊠ None □ System fault ☑ Fault □ Trouble ☑ Quick stop by trouble ☑ Warning locked □ Warning ☑ Information	
Cause	Remedy
<ul> <li>The data exchange via PROFINET has been terminated.</li> <li>Also see the chapter "<u>Interruption of PROFINET</u> <u>communication</u>" (<u>171</u>).</li> </ul>	<ul> <li>Check cables and terminals.</li> <li>Connect network cable to PROFINET connections.</li> </ul>

#### PROFINET: Station name error [0x01bc6532]

Response (Lenze setting printed in bold)	Setting: not possible
□ No reaction □ System fault	
Cause	Remedy
Station name is not DNS-conform.	Use a DNS-compliant station name. • <u>Setting the station name</u> (🖽 36)

#### PROFINET: IP address error [0x01bc6533]

Response (Lenze setting printed in bold)	Setting: not possible
🗆 No reaction 🗆 System fault 🗵 Fault 🗆 Trouble 🗆 Quick stop by trouble 🗆 WarningLocked 🗆 Warning 🗆 Information	
Cause	Remedy
An invalid IP address has been assigned by the I/O controller via PROFINET or has been set in code <u>C13000</u> .	<ul> <li>Make sure that the I/O controller has assigned a valid IP address via PROFINET.</li> <li>Set a valid IP address.</li> <li><u>Setting the IP configuration</u> ( 38)</li> </ul>

#### PROFINET: Stack init error [0x01bc6534]

Response (Lenze setting printed in bold)	Setting: not possible			
□ No reaction □ System fault	uble 🗆 WarningLocked 🗆 Warning 🗆 Information			
Cause	Remedy			
The stack cannot be initialised with the parameters se- lected by the user. This may be due to a station name which does not comply with the PROFINET specification.	Check and, if necessary, adapt PROFINET parameters: • <u>Setting the IP configuration</u> ( 38) • <u>Setting the station name</u> ( 36)			

#### PROFINET: Internal error [0x01bc6650]

Response (Lenze setting printed in bold)	Setting: not possible			
□ No reaction □ System fault	ouble  □ WarningLocked  □ Warning  □ Information			
Cause	Remedy			

Parameters of the communication module

## **13** Parameter reference

[ALinkKeywords] Parameters This chapter supplements the parameter list and the table of attributes for the Inverter Drive 8400 contained in the software manual and in the »Engineer« online help by the parameters of the communication module E84AYCER (PROFINET).



Software manual/»Engineer« online help for the Inverter Drive 8400

Here you will find general information on parameters.

[Search-Keywords] Hlp\_Para

## 13.1 Parameters of the communication module

This chapter lists the parameters of the E84AYCER communication module (PROFINET) in numerically ascending order.



## Note!

### **PROFINET command "Reset to Factory Defaults"**

If the "Reset to factory defaults" PROFINET command is executed by an IO supervisor or an I/O controller, the PROFINET-specific parameters will be reset to their standard values:

- <u>C13000</u> | IP address
- C13001 | Subnetwork mask
- <u>C13002</u> | Gateway address
- C13010 | Active IP address
- C13011 | Active subnetwork mask
- C13012 | Active gateway address
- C13864 | Active station name
- C13887 | Suppress signalling diag. mess. upon
- C13899 | Station name
- <u>C13910</u> | I&M1 system designation
- C13911 | I&M1 installation site
- C13912 | I&M2 installation date
- C13913 | I&M3 additional information
- <u>C13914</u> | I&M4 signature code

Parameter   Name: C13000   IP addres	s			Data type: UNSIGNED_32 Index: 11575 <sub>d</sub> = 2D37 <sub>h</sub>	
Setting of the IP ac <u>Setting the IP co</u>					
Setting range (min.	Setting range (min. value   unit   max. value) Lenze setting				
0		4294967295	0		
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT					

Parameters of the communication module

#### C13001

Parameter   Name: C13001   Subnetw	ork mask			Data type: UNSIGNED_32 Index: 11574 <sub>d</sub> = 2D36 <sub>h</sub>	
Setting of the subr <u>Setting the IP co</u>					
Setting range (min. value   unit   max. value) Lenze setting					
0 4294967295 <b>0</b>					
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT					

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### C13002

Parameter   Name: C13002   Gateway	address			Data type: UNSIGNED_32 Index: 11573 <sub>d</sub> = 2D35 <sub>h</sub>	
Setting of the gate Setting the IP co					
Setting range (min. value   unit   max. value) Lenze setting					
0		4294967295	0		
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT					

Parameter   Name: C13003   Physical address	Data type: OCTET_STRING Index: 11572 <sub>d</sub> = 2D34 <sub>h</sub>
Display of the MAC-ID	
Subcodes	Info
C13003/1	MAC ID: Station
C13003/2	MAC ID: Port1
C13003/3	MAC ID: Port2
☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □	] PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT

Parameters of the communication module

#### C13010

Parameter   Name: C13010   Active IP address	Data type: UNSIGNED_8 Index: 11565 <sub>d</sub> = 2D2D <sub>h</sub>			
<ul> <li>Display of the active IP address</li> <li>The active IP address may differ from the contents of code <u>C13000</u>, depending on whether the station name was changed via the fieldbus or the parameter.</li> </ul>				
Subcodes	Info			
C13010/1	Active IP address.1			
C13010/2	Active IP address.2			
C13010/3	Active IP address.3			
C13010/4	Active IP address.4			
☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □	」 PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT			

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#### C13011

Parameter   Name: C13011   Active su	bnetwork mask			Data type: UNSIGNED_8 Index: 11564 <sub>d</sub> = 2D2C <sub>h</sub>		
Display of the active subnetwork mask • The active subnetwork mask may differ from the contents of code <u>C13001</u> , depending on whether the station name was changed via the fieldbus or the parameter.						
Display range (min. value   unit   max. value)						
0		255				
Subcodes Info						
C13011/1 Active subnetwork mask.1						
C13011/2			Active subnetwork mask.2			
C13011/3			Active subnetwork mask.3			
C13011/4 Active subnetwork mask.4						
🗹 Read access 🛛 Write	e access 🗆 CINH 🗆 PLC	-STOP 🗆 No transfer 🗆	] PDO_MAP_RX	□ MOT		

Parameter   Name: C13012   Active ga	teway address			Data type: UNSIGNED_8 Index: 11563 <sub>d</sub> = 2D2B <sub>h</sub>		
Display of the active gateway address • The active gateway address may differ from the contents of code <u>C13002</u> , depending on whether the station name was changed via the fieldbus or the parameter.						
Display range (min.	value   unit   max. value)					
0		255				
Subcodes Info						
C13012/1			Active gateway address.1			
C13012/2			Active gateway address.2			
C13012/3			Active gateway address.3			
C13012/4			Active gateway address.4			
🗹 Read access 🛛 Write	e access 🗆 CINH 🗆 PLC	-STOP 🗆 No transfer 🛛		□ MOT		

Parameters of the communication module

#### C13850

Parameter   Name: C13850   All words to master					Data type: UNSIGNED_16 Index: 10725 <sub>d</sub> = 29E5 <sub>h</sub>		
Display of the prod In the subcodes 1 t cess data words a	Display of the process data words which are transmitted from the inverter to the IO controller. In the subcodes 1 to 16, all process data words to the I/O controller are displayed. However, only the configured pro- cess data words are valid.						
Display range (min.	value   unit   max. value)						
0		65535					
Subcodes	Subcodes						
C13850/1							
C13850/16							
☑ Read access □ Write	□ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT				□ MOT		

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#### C13851

Parameter   Name: C13851   All wor	Data type: UNSIGNED_16 Index: 10724 <sub>d</sub> = 29E4 <sub>h</sub>					
Display of the process data words which are transmitted from the IO controller to the inverter. In the subcodes 1 to 16, all process data words from the I/O controller are displayed. However, only the configured process data words are valid.						
Display range (mi	n. value   unit   max. value)	)				
0		65535				
Subcodes			Info			
C13851/1						
C13851/16						
☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □ PDO MAP RX □ PDO MAP TX □ COM □ MOT						

Parameter   Name: C13852   All words to standard device						Data type: UNSIGNED_16 Index: 10723 <sub>d</sub> = 29E3 <sub>h</sub>	
Display of the pro	cess data word	ds 1 16, v	which are trans	mitted from	the IO control	ler to the	e inverter.
Display range (min	. value   unit   max	. value)					
0			65535	-			
Subcodes			Info				
C13852/1							
C13852/16							
🗹 Read access 🛛 Writ	e access 🗆 CINH	D PLC-STOP	□ No transfer [	⊐ PDO_MAP_RX	D PDO_MAP_TX	□ сом	□ MOT

Parameters of the communication module

#### C13853

Parameter   Name: C13853   All words from standard device				Data type: UNSIGNED_16 Index: 10722 <sub>d</sub> = 29E2 <sub>h</sub>
Display of the proc	ess data words 1	16, which are trans	mitted from the inverter to the IC	controller.
Display range (min. value   unit   max. value)				
0		65535		
Subcodes		Info		
C13853/1				
C13853/16				
☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □			□ PDO_MAP_RX □ PDO_MAP_TX □ COM	□ MOT

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#### C13860

Parameter   Name: C13860   Settings				Data type: UNSIGNED_8 Index: 10715 <sub>d</sub> = 29DB <sub>h</sub>
Display range (min. value   unit   max. value)				
0		255		
Subcodes		Info		
C13860/1			Reserved	
C13860/2			Number of process data words	
C13860/3			Reserved	
C13860/4			Reserved	
🗹 Read access 🛛 Write	e access 🗆 CINH 🗆 PLC	-STOP 🗆 No transfer 🛛	] PDO_MAP_RX □ PDO_MAP_TX □ COM	□ MOT

Parameter   Name: C13861   Bus statu	IS				Data type: BITFIELD_16 Index: 10714 <sub>d</sub> = 29DA <sub>h</sub>
Bit-coded display o	of current bus status				
Value is bit-coded	:				
Bit 0	Initialised				
Bit 1	Online				
Bit 2	Connected				
Bit 3	Address conflict				
Bit 4	Hardware error				
Bit 5	EEPROM error				
Bit 6	Watchdog error				
Bit 7	Protocol error				
Bit 8	Profinet stack ok				
Bit 9	Profinet stack not configured				
Bit 10	Ethernet controller error				
Bit 11	UDP stack error				
Bit 12	Reserved				
Bit 13	Reserved				
Bit 14	Reserved				
Bit 15	Reserved				
🗹 Read access 🛛 Write	e access □CINH □PLC-STOP □No transfer □	] PDO_MAP_RX [	□ PDO_MAP_TX	□ сом	□ МОТ

Parameters of the communication module

#### C13862

Parameter   Name: C13862   Bus counter			Data type: UNSIGNED_32 Index: 10713 <sub>d</sub> = 29D9 <sub>h</sub>	
Display of the data	a cycles per seco	nd (independent of dat	a changes)	
Display range (min.	value   unit   max. v	alue)		
0		4294967295		
Subcodes		Info		
C13862/1		Data cycles per second		
C13862/2		Read cycles per second		
C13862/3		Write cycles per second		
🗹 Read access 🛛 Write	☐ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT			

Parameter   Name: C13864   Active station name	Data type: VISIBLE_STRING Index: 10711 <sub>d</sub> = 29D7 <sub>h</sub>			
Displays the active station name used by the inverter. It may differ from the contents of code <u>C13899</u> , depending on whether the station name has been changed via the fieldbus or via <u>C13899</u> . <u>Setting the station name</u> (C) 36)				
Subcodes	Info			
C13864/1	1st 30th character			
C13864/2	31th 60th character			
C13864/3	61th 90th character			
C13864/4	91th 120th character			
C13864/5	121th 150th character			
C13864/6	151th 180th character			
C13864/7	181th 210th character			
C13864/8	211th 240th character			
☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □	DPDO_MAP_RX □ PDO_MAP_TX □ COM	П МОТ		

Parameters of the communication module

#### C13867

Parameter   Name: C13867   Display: Most recent diagnostic data	Data type: OCTET_STRING Index: 10708 <sub>d</sub> = 29D4 <sub>h</sub>
Display of the diagnostic data sent by the inverter most recently.	
Read access Write access CINH PLC-STOP No transfer PDO_MAP_RX PDO_MAP_TX COM	□ MOT

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Bytes	Information
0	Slot
1	
2	Subslot
3	
4	Error code
7	
8	Slot
9	
10	Subslot
11	
12	Error code
15	

Parameter   Name: C13877   Bus error	Parameter   Name: Data type: UNSIGNED_ <b>C13877   Bus error(1)</b> Data type: 29C				
The code contains • The error value	The code contains the error currently detected on the fieldbus. • The error values can occur in combination with the error values from code <u>C13878</u> .				
Selection list (read of	only)	Info			
0	No error				
1	Internal error				
2	Unit ID unknown				
3	Max. units exceeded				
4	Invalid size				
5	Unit type unknown				
6	Runtime plug				
7	Invalid argument				
8	Service pending				
9	Stack not ready				
10	Command unknown				
11	Invalid address descriptor				
12	Watchdog expired				
13	Protocol not supported				
☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT					

Parameters of the communication module

#### C13878

Parameter   Name: C13878   Bus error(2)			Data type: BITFIELD_16 Index: 10697 <sub>d</sub> = 29C9 <sub>h</sub>		
The code contains • The error value	The code contains the error currently detected on the fieldbus. • The error values can occur in combination with the error values from code <u>C13877</u> .				
Value is bit-coded		Info			
Bit 0	Reserved				
Bit 6	Reserved				
Bit 7	IP address error				
Bit 8	Station name error				
Bit 9	DataExch left				
Bit 10	Stack boot error				
Bit 11	Stack online error				
Bit 12	Stack state error				
Bit 13	Stack revision error				
Bit 14	Stack init error				
Bit 15	Stack CPU boot error				
🗹 Read access 🛛 Write	☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT				

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#### C13880

Parameter   Name: C13880   Monitori	Data type: UNSIGNED_8 Index: 10695 <sub>d</sub> = 29C7 <sub>h</sub>		
The action set in so DATA_EXCHANGE • Please also obs • A change in the	ubcode 1 of the code is carried out whe status. erve the notes provided in code <u>C1388</u> monitoring response becomes immed	n the node recognises that it is no <u>1</u> . liately effective.	longer in the
Selection list			
0	No response		
1	Error		
3	Quick stop by trouble		
4	Warning Locked		
6	Information		
Subcodes	Lenze setting	Info	
C13880/1	0: No Response	"Watchdog/Data Exchange" moni	toring
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT			

Parameter   Name: C13881   Reaction time delay			Data type: UNSIGNED_16 Index: 10694 <sub>d</sub> = 29C6 <sub>h</sub>	
If the DATA_EXCHANGE status is exited, the response parameterised in <u>C13880</u> is activated after the time set her has elapsed. • A value of "65535" in this code deactivates the monitoring function. • A change of monitoring will be effective immediately.				
Setting range (min. value   unit   max. value) Lenze setting				
0	ms	65535	0 ms	
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT				

Parameters of the communication module

#### C13885

Parameter   Name: C13885   Clear process data			Data type: UNSIGNED_8 Index: 10690 <sub>d</sub> = 29C2 <sub>h</sub>
This code is used to set the process data that are to be processed by the I/O device in order to maintain the internation munication when the PROFINET has left the DATA_EXCHANGE status.			
Selection list (Lenze setting printed in bold)		Info	
0 Use of most recent master PDOs		The last data sent by the I/O contr	roller are used.
<b>1 PDOs are set to the value 0'</b> The contents of the pro		The contents of the process data a	are set to the value "0".
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT			

#### C13887

Parameter   Name: C13887   Suppress	Data type: BITFIELD_8 Index: 10688 <sub>d</sub> = 29C0 <sub>h</sub>					
<ul> <li>This code serves to inhibit the transmission of alarm messages to the IO controller. By this, errors of a specific type can be systematically suppressed. All errors are furthermore entered in the logbook.</li> <li>A change will only be effective immediately if no error number with the error type selected here is active in stan dard device code C00165.</li> </ul>						
Value is bit-coded: Info						
Bit 0	Error					
Bit 1	Fault					
Bit 2	Quick stop by trouble					
Bit 3	Warning Locked					
Bit 4	Warning					
Bit 5	Information					
Bit 6	Reserved					
Bit 7	Connection to 8400 lost					

Parameter   Name: C13899   Station n	Data type: VISIBLE_STRING Index: 10676 <sub>d</sub> = 29B4 <sub>h</sub>					
<ul> <li>The name with a max. length of 240 characters is distributed to the subindices. The name can be entered starting with subindex 1. The following unused subindices are not relevant.</li> <li>The station name must be assigned in accordance with the PROFINET specification. In the standard setting a deleted name is displayed. The name is also deleted if the "Reset to factory defaults" command is executed by an IO supervisor or an I/O controller.</li> <li>A change of the station name will only become effective by switching the mains of the inverter.</li> <li>Setting the station name (</li></ul>						
Subcodes	Lenze setting Info					
C13899/1		1st 30th character				
C13899/2		31th 60th character				
C13899/3		61th 90th character				
C13899/4		91th 120th character				
C13899/5		121th 150th character				
C13899/6		151th 180th character				
C13899/7		181th 210th character				
C13899/8		211th 240th character				
Image: Construction of the second						

Parameters of the communication module

#### C13900

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Parameter   Name: C13900   Firmware product type	Data type: VISIBLE_STRING Index: 10675 <sub>d</sub> = 29B3 <sub>h</sub>
The code contains a string with a length of 8 characters. The "E84DFYER" identification code is output.	
☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □ PDO MAP RX □ PDO MAP TX □ COM	□ MOT

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#### C13901

Parameter   Name: C13901   Firmware compilation date	Data type: VISIBLE_STRING Index: 10674 <sub>d</sub> = 29B2 <sub>h</sub>
The code contains a string with a length of 20 characters. The creation date ("MMM DD YYYY") and time ("hh:mm:ss") of the software are displayed, e 12:31:21".	.g. "Mar 21 2005

#### C13902

Parameter   Name: C13902   Firmware version	Data type: VISIBLE_STRING Index: 10673 <sub>d</sub> = 29B1 <sub>h</sub>
The code contains a string with a length of 11 characters. The identification code is displayed (e.g. "01.00.00.00").	
☑ Read access □ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM	□ МОТ

#### C13910

Parameter   Name: C13910   I&M1 System designation	Data type: VISIBLE_STRING Index: 10665 <sub>d</sub> = 29A9 <sub>h</sub>
Input/output of the I&M1 plant identification code <ul> <li>The Lenze setting shows an empty string.</li> </ul>	
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM	□ МОТ

#### C13911

Parameter   Name: C13911   I&M1 Installation site	Data type: VISIBLE_STRING Index: 10664 <sub>d</sub> = 29A8 <sub>h</sub>
Input/output of the I&M1 location identification code <ul> <li>The Lenze setting shows an empty string.</li> </ul>	
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM	□ МОТ

Parameter   Name: C13912   I&M2 Installation date	Data type: VISIBLE_STRING Index: 10663 <sub>d</sub> = 29A7 <sub>h</sub>
Input/output of the I&M2 date of installation • The Lenze setting shows an empty string.	
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM	□ MOT

Parameters of the communication module

#### C13913

Parameter   Name: C13913   I&M3 ad	Data type: VISIBLE_STRING Index: 10662 <sub>d</sub> = 29A6 <sub>h</sub>				
Input/output if the • The Lenze setting					
Subcodes	Lenze setting	Info			
C13913/1		I&M3 additional information			
C13913/2 I&M3 additional information					
☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT					

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Parameter   Name: C13914   I&M4 sig	Data type: OCTET_STRING Index: 10661 <sub>d</sub> = 29A5 <sub>h</sub>					
Input/output of th						
Subcodes	Lenze setting	Info				
C13914/1	00000000000000000000000000000000000000	I&M4 signature code				
C13914/2						
🗹 Read access 🗹 Write	☑ Read access ☑ Write access □ CINH □ PLC-STOP □ No transfer □ PDO_MAP_RX □ PDO_MAP_TX □ COM □ MOT					

Table of attributes

## 13.2 Table of attributes

The table of attributes contains information that is required for communication with the inverter via parameters.

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### How to read the table of attributes:

Column		Meaning	Entry		
Code		Parameter name	Сххххх		
Name		Parameter short text (display text)	Text		
Index	dec	Index under which the parameter is addressed.	24575 - Lenze code number	Is only required for access via a bus sys-	
	hex	The subindex for array variables corresponds to the Lenze subcode number.	5FFF <sub>h</sub> - Lenze code number	tem.	
Data	DS	Data structure	E	Single variable (only one parameter element)	
			A	Array variable (several parameter elements)	
	DA	Number of array elements (subcodes)	Number		
	DT	Data type	BITFIELD_8	1 byte, bit-coded	
			BITFIELD_16	2 bytes, bit-coded	
			BITFIELD_32	4 bytes, bit-coded	
			INTEGER_8	1 byte, with sign	
			INTEGER_16	2 bytes with sign	
			INTEGER_32	4 bytes, with sign	
			UNSIGNED_8	1 byte without sign	
			UNSIGNED_16	2 bytes without sign	
			UNSIGNED_32	4 bytes, without sign	
			VISIBLE_STRING	ASCII string	
			OCTET_STRING		
	Factor Factor for data transmission via a bus system, depending on the number of decimal positions		Factor	1 = No decimal positions 10 = 1 decimal position 100 = 2 decimal positions 1000 = 3 decimal positions	
Access	R	Read access	☑ Reading permitted		
	w	Write access	☑ Writing permitted		
	CINH	Controller inhibit required	☑ Writing is only possible if controller inhibit is set		

Table of attributes

## Table of attributes

Code	Name	Inc	lex		Data		Access			
		dec	hex	DS	DA	Data type	Factor	R	w	CINH
<u>C13000</u>	IP address	11575	2D37	E	1	UNSIGNED_32	1	Ø	Ø	
<u>C13001</u>	Subnet Mask	11574	2D36	E	1	UNSIGNED_32	1	Ø	Ø	
<u>C13002</u>	Gateway address	11573	2D35	E	1	UNSIGNED_32	1	Ø		
<u>C13003</u>	Physical address	11572	2D34	Α	3	OCTET_STRING		Ø		
<u>C13010</u>	Active IP Address	11565	2D2D	Α	4	UNSIGNED_8	1	Ø		
<u>C13011</u>	Active Subnetwork Mask	11564	2D2C	Α	4	UNSIGNED_8	1	Ø		
<u>C13012</u>	Active IP Address	11563	2D2B	Α	4	UNSIGNED_8	1	Ø		
<u>C13850</u>	All words from drive to master	10725	29E5	A	16	UNSIGNED_16	1	Ø		
<u>C13851</u>	All words from master to drive	10724	29E4	A	16	UNSIGNED_16	1	Ø		
<u>C13852</u>	All words to the basic device	10723	29E3	A	16	UNSIGNED_16	1	Ø		
<u>C13853</u>	All words to the basic device	10722	29E2	A	16	UNSIGNED_16	1	Ø		
<u>C13860</u>	Settings	10715	29DB	A	4	UNSIGNED_8	1	Ø		
<u>C13861</u>	Bus status	10714	29DA	E	1	BITFIELD_16		Ø		
<u>C13862</u>	Bus counter	10713	29D9	A	3	UNSIGNED_32	1	Ø		
<u>C13864</u>	Active station name	10711	29D7	A	8	VISIBLE_STRING		Ø		
<u>C13867</u>	Display: Most recent diagnostic data	10708	29D4	E	1	OCTET_STRING		Ø		
<u>C13877</u>	Bus error(1)	10698	29CA	E	1	UNSIGNED_16	1	Ø		
<u>C13878</u>	- Bus error(2)	10697	29C9	E	1	BITFIELD_16		Ø		
<u>C13880</u>	Monitoring Reaction	10695	29C7	A	1	UNSIGNED_8	1	Ø		
<u>C13881</u>	Reaction time delay	10694	29C6	E	1	UNSIGNED_16	1	Ø		
<u>C13885</u>	Delete process data	10690	29C2	E	1	UNSIGNED_8	1	Ø		
<u>C13887</u>	Suppress signalling diag. mess. upon	10688	29C0	E	1	BITFIELD_8		Ø		
<u>C13899</u>	Station name	10676	29B4	A	8	VISIBLE_STRING		Ø		
<u>C13900</u>	Firmware Product Type	10675	29B3	E	1	VISIBLE_STRING		Ø		
<u>C13901</u>	Firmware Compilation Date	10674	29B2	E	1	VISIBLE_STRING		Ø		
<u>C13902</u>	Firmware Version	10673	29B1	E	1	VISIBLE_STRING		Ø		
<u>C13910</u>	I&M1 system designation	10665	29A9	E	1	VISIBLE_STRING		Ø		
<u>C13911</u>	I&M1 installation site	10664	29A8	E	1	VISIBLE_STRING		Ø	Ø	
<u>C13912</u>	I&M2 installation date	10663	29A7	E	1	VISIBLE_STRING		Ø	Ø	
<u>C13913</u>	I&M3 additional information	10662	29A6	А	2	VISIBLE_STRING		Ø	Ø	
<u>C13914</u>	I&M4 signature code	10661	29A5	Α	2	OCTET_STRING		Ø		

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